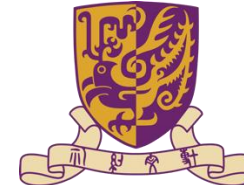




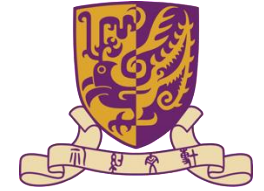
Abstract from  
Unit 1 - AI Basics (II),  
Module on Artificial  
Intelligence for Junior  
Secondary Level (Booklet 2)



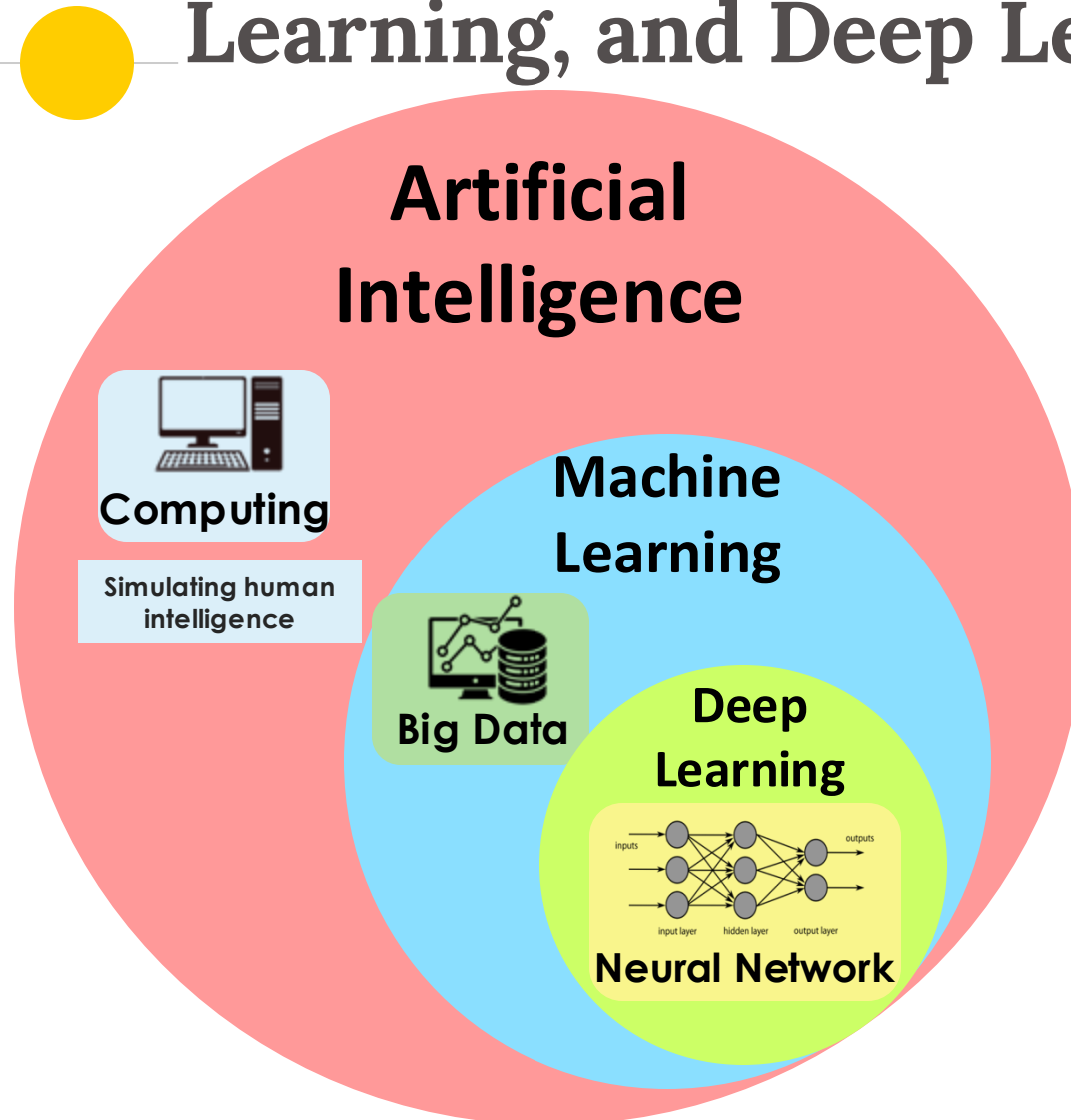
1

# Experience AI Model Training and Testing with Teachable Machine

- Introduction to Artificial Neural Network
- Model Training and Testing Process
- Impact of Using Contaminated Training Dataset
- Apply AI Model in Hardware Development



# Artificial Intelligence, Machine Learning, and Deep Learning



## History of AI

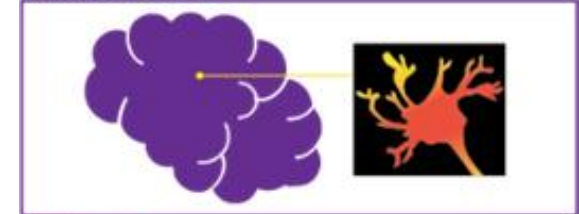




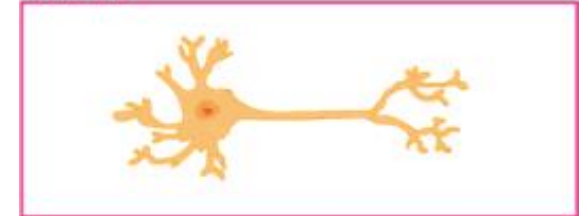
# Artificial Neural Networks

- An **artificial neural network (ANN)** is a class of machine learning models that is inspired by human brain.
- A **perceptron** in a neural network resembles a neuron in the human brain.
- A **deep neural network (DNN)** is an ANN with many layers.
- At a very high level, neural networks resembled the human brain because they consist of many connected perceptrons.

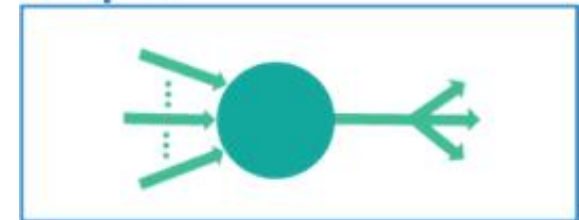
Human Brain

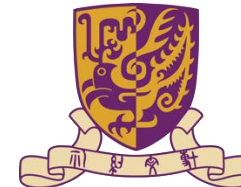


Neuron



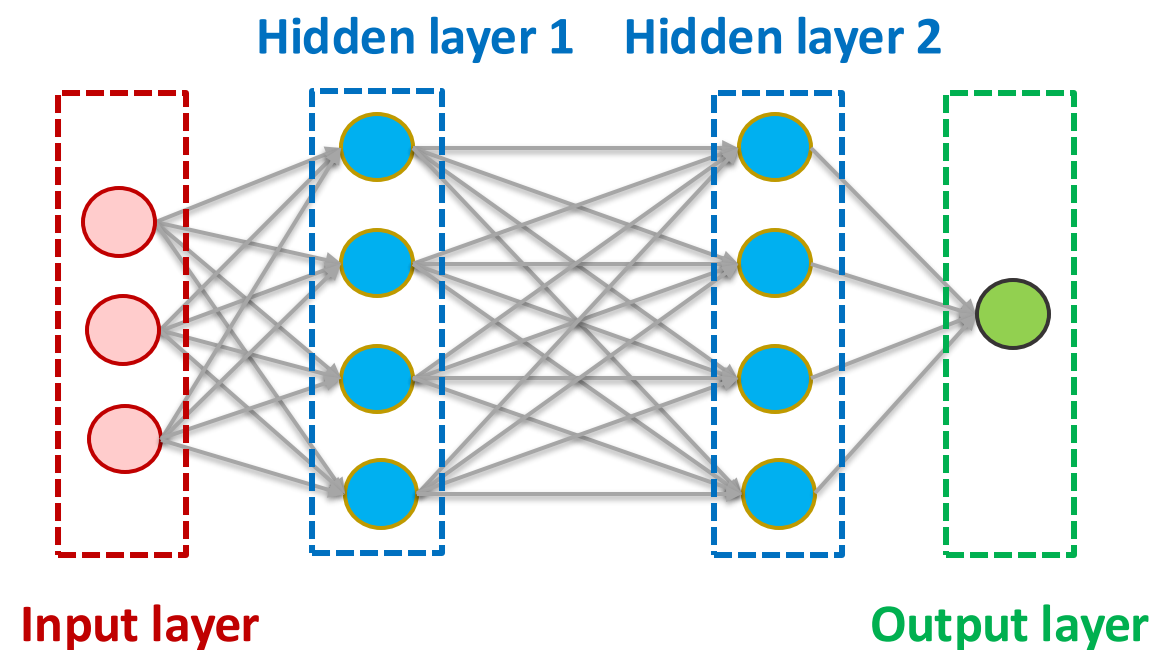
Perceptron

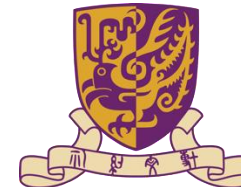




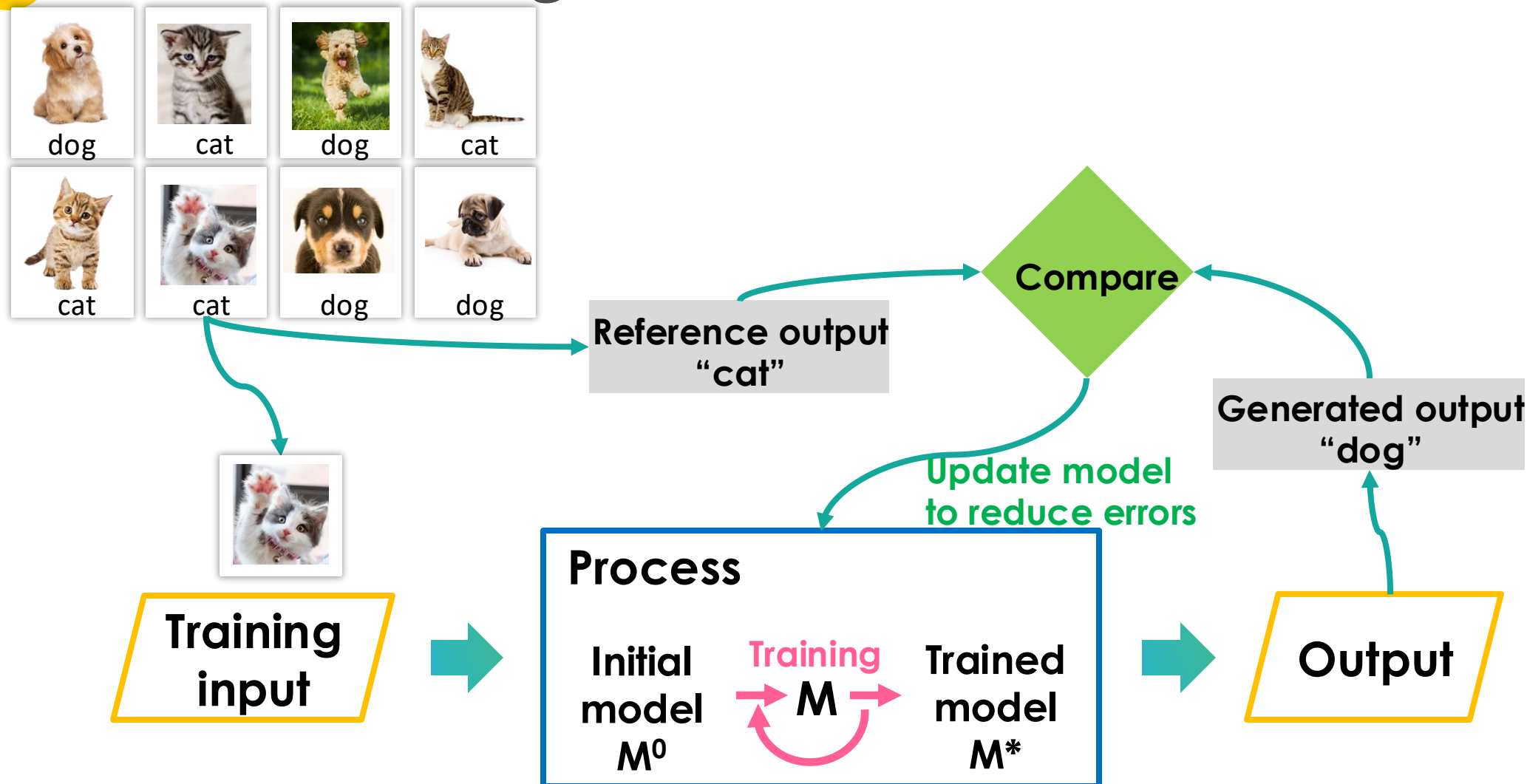
# Deep Neural Networks

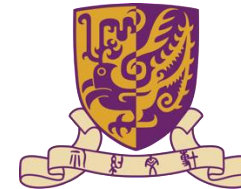
- A DNN is composed of 3 types of layers:
  - Input Layer
    - Receive input data
  - Hidden Layers
    - Perform computations
  - Output Layer
    - Deliver output



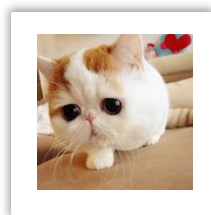


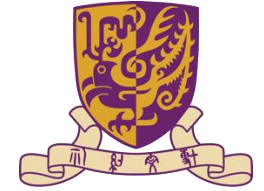
# Model Training





# ● Model testing

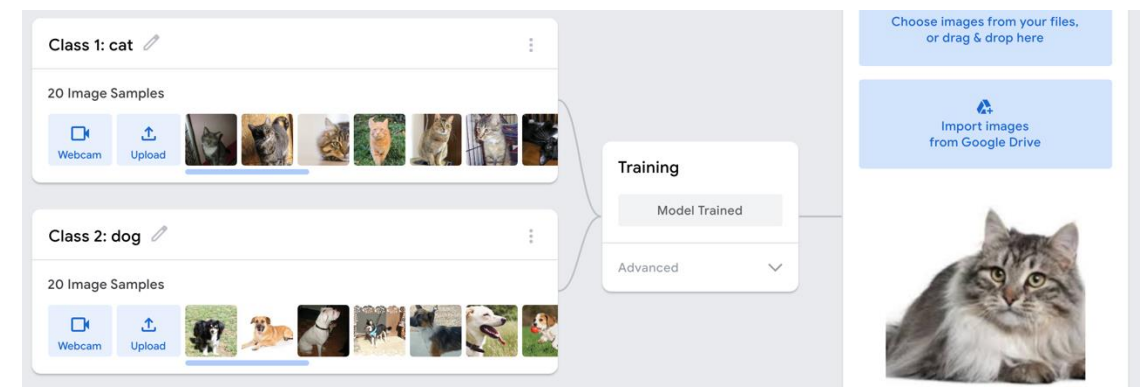




## Activity 1-4

- Let's train a cat dog classifier model with:
  - Normal Dataset**
  - Small Dataset**
  - Noisy Dataset**
  - Unbalanced Dataset**

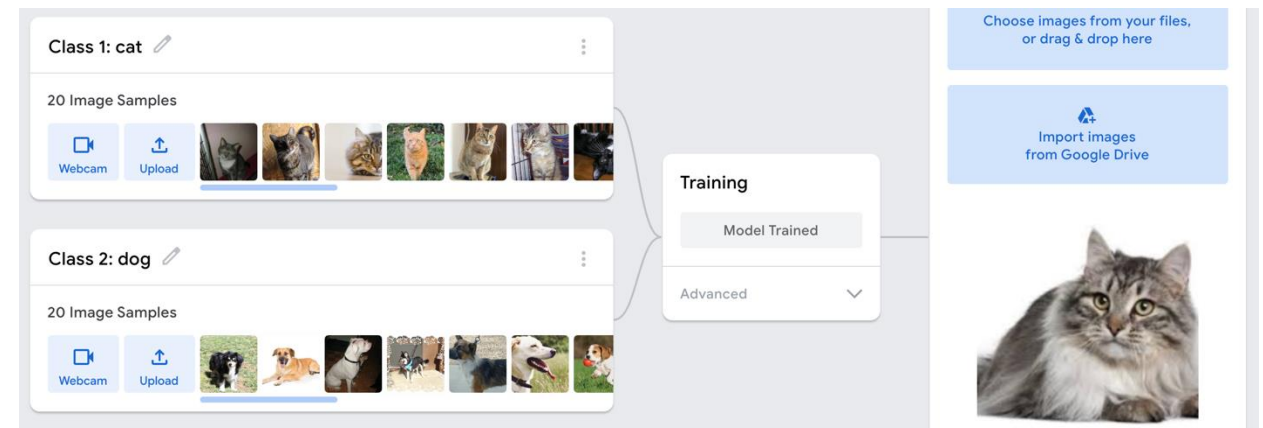
Topic	*Task
1.1 Model Training and Testing	1
1.2 Problems in Training Data	2
	3 & 4



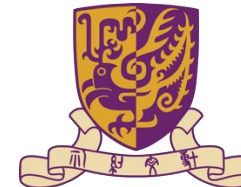


# Activity 1: Model training and testing (image classifier)

1. Visit <https://teachablemachine.withgoogle.com/>
2. Download dataset at <https://shorturl.at/ikGI1>
3. Use Activity 1's dataset to train the AI model







## Activity 2: Training with A Small Dataset

1. Re-train the model with Activity 2's dataset
2. Test the model with the testing image

Class 1: cat

**Small training dataset**

1 Image Samples

Class 2: dog

1 Image Samples

**Training**

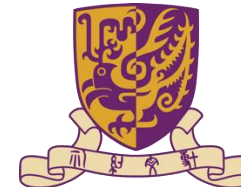
Model Trained

Advanced

Choose images from your files,  
or drag & drop here

Import images  
from Google Drive

Testing  
image



## Activity 3: Training with A Noisy Dataset

1. Re-train the model with Activity 3's dataset

**Noisy training dataset**

Class 1: cat

4 Image Samples

Webcam Upload

Class 2: dog

5 Image Samples

Webcam Upload

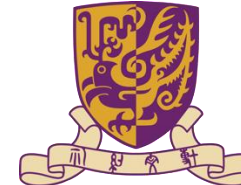
Training

Model Trained

Advanced

Choose images from your files, or drag & drop here

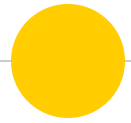
Testing image



## Activity 4: Training with An Unbalanced Dataset

1. Re-train the model with Activity 4's dataset

The screenshot displays a machine learning training interface. On the left, there are two class categories: 'Class 1: cat' and 'Class 2: dog'. 'Class 1: cat' has 1 image sample, while 'Class 2: dog' has 13 image samples. A yellow box highlights a section titled 'Unbalanced training dataset: 1 cat vs 10 dogs', which shows a single cat image and ten dog images. In the center, a 'Training' panel indicates 'Model Trained' and 'Advanced' settings. On the right, a 'Testing image' section shows a single cat image. Above the testing image, there are instructions to 'Choose images from your files, or drag & drop here' and a button to 'Import images'.



# Issues in Input Data

## Data Authenticity:

Ensure provided data is **original** and from a **trusted source**

## Data Bias:

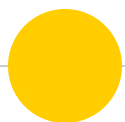
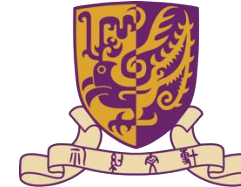
**Avoid unbalanced data** or **under-representation** of categories in data

## Data Security:

**Protected** from corruption and unauthorized access

## Data Privacy:

Use of data with **providers' consent**



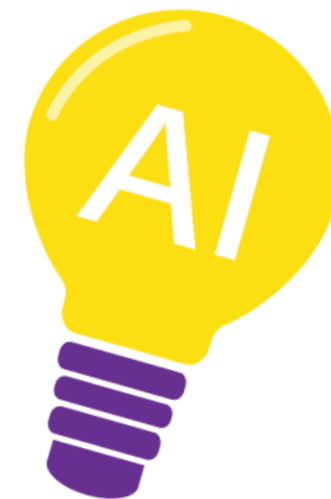
## Activity Summary



**AI system development:** AI can learn from labelled training data to produce a trained model for a target task, and apply the trained model on new (unlabelled) testing data.

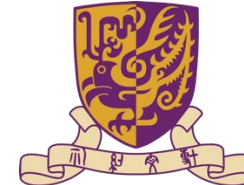


**The quality of training data is important:** A well-trained AI model requires a large amount of data, accurately labelled (i.e. low noise), and well-balanced (i.e. low bias). The quality of data affects the performance of the AI model. High quality data causes high model performance; low quality data causes low model performance. Garbage in (useless data input) leads to garbage out (useless information output).





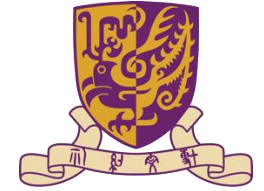
Extra activity for  
Unit 2 – AI Ethical Issues,  
Module on Artificial  
Intelligence for Junior  
Secondary Level (Booklet 2)



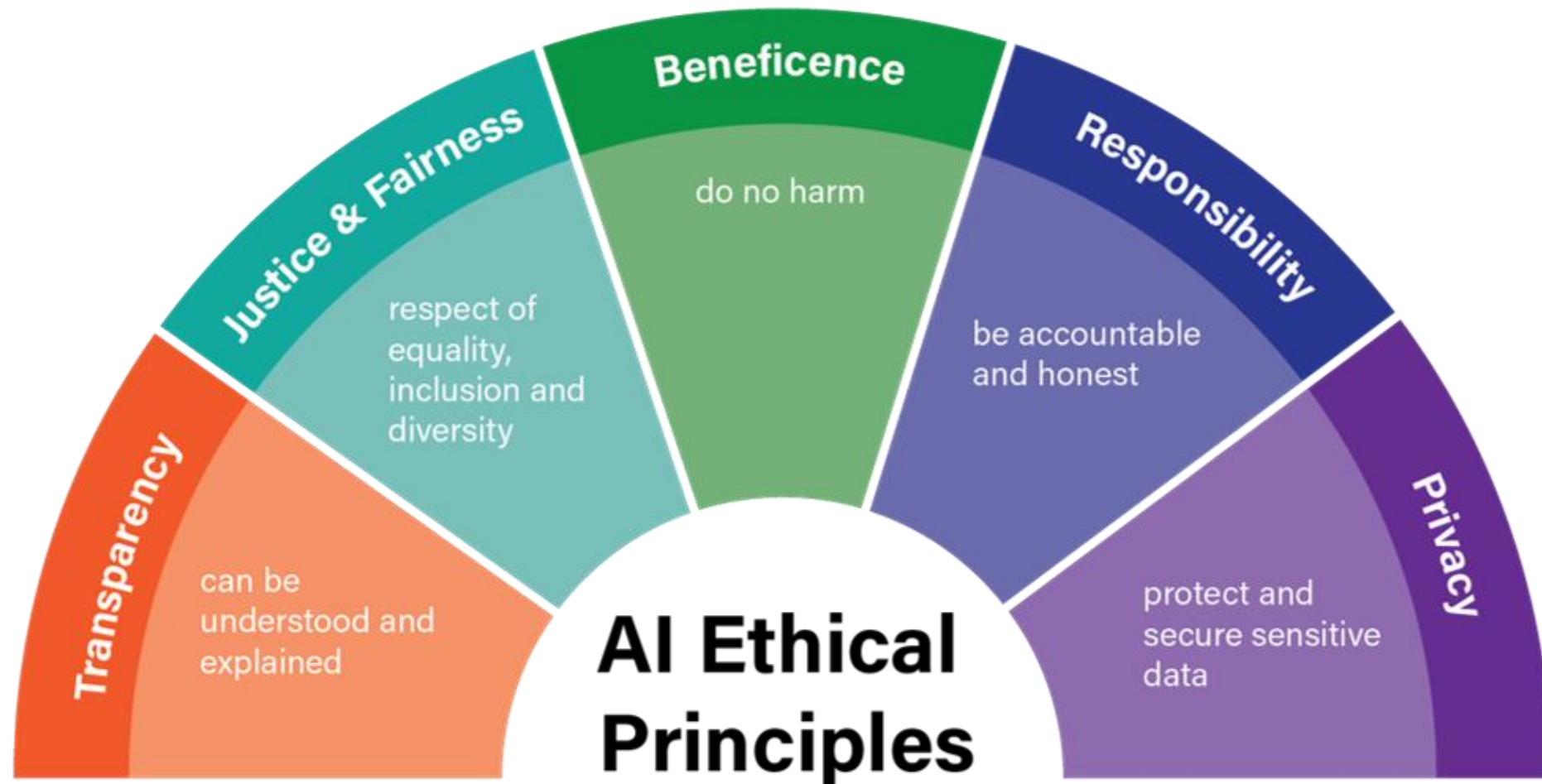
2

# Moral Dilemma Experiment with CUHK-JC iCar

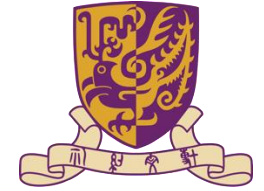
- Common AI Ethical Principles
- Introduction to CUHK-JC iCar
- Experience Blockly Programming and AI Model Training Process with Moral Dilemma Experiment



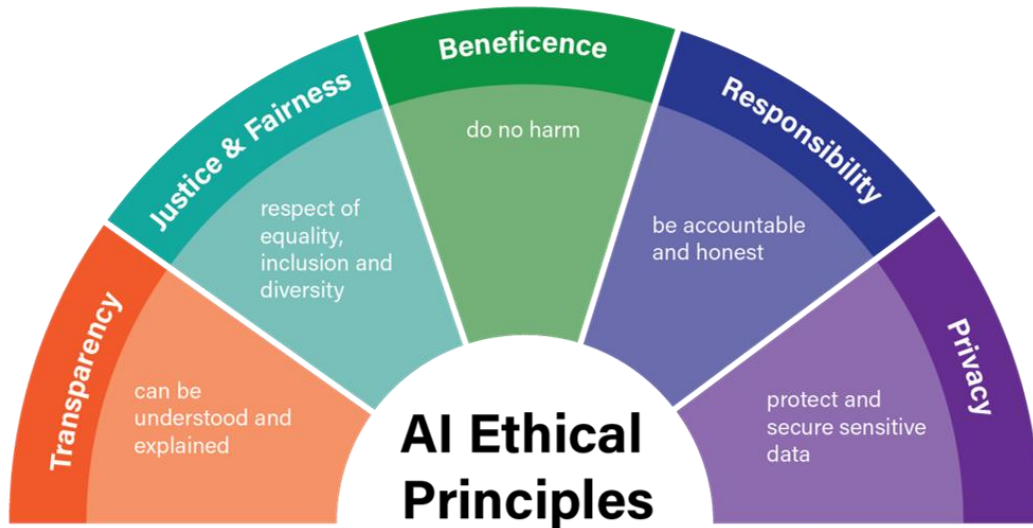
# Five Most Common AI Ethical Principles





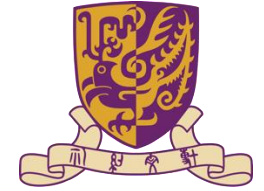


# Five Most Common AI Ethical Principles

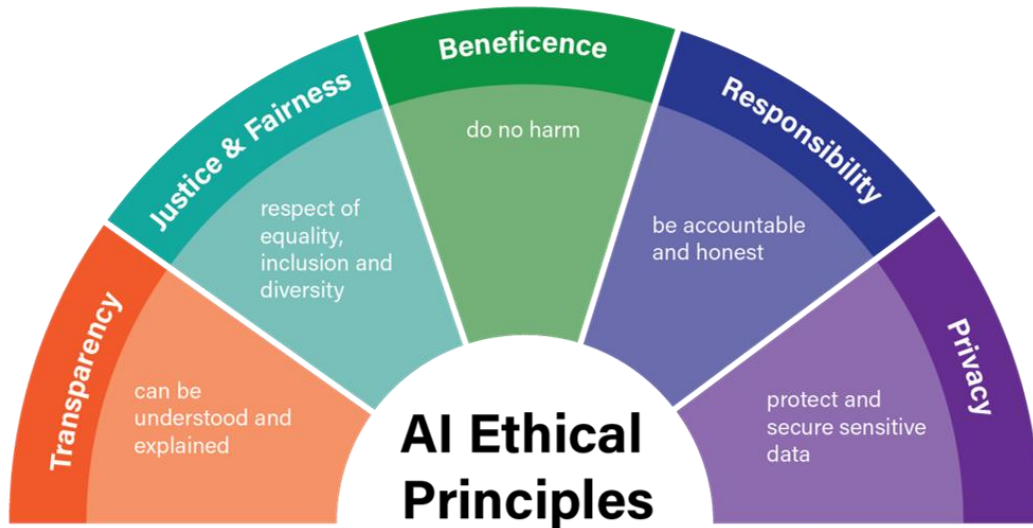


1. **Transparency**: Ensure that AI-enabled processing in applications can be interpretable by and explainable to users
2. **Justice and fairness**: Development of AI technologies and their applications must ensure equality, inclusion and diversity
3. **Beneficence**: Development and application of AI technologies must not do any harm



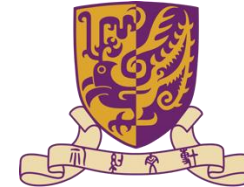


# Five Most Common AI Ethical Principles

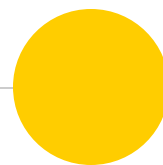


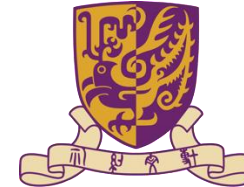
4. **Responsibility**: Development and application of AI technologies must uphold accountability and honesty

5. **Privacy**: While developing AI technologies and incorporating them into real applications, sensitive data must be protected and secured



# Introduction to CUHK-JC iCar

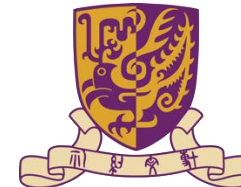




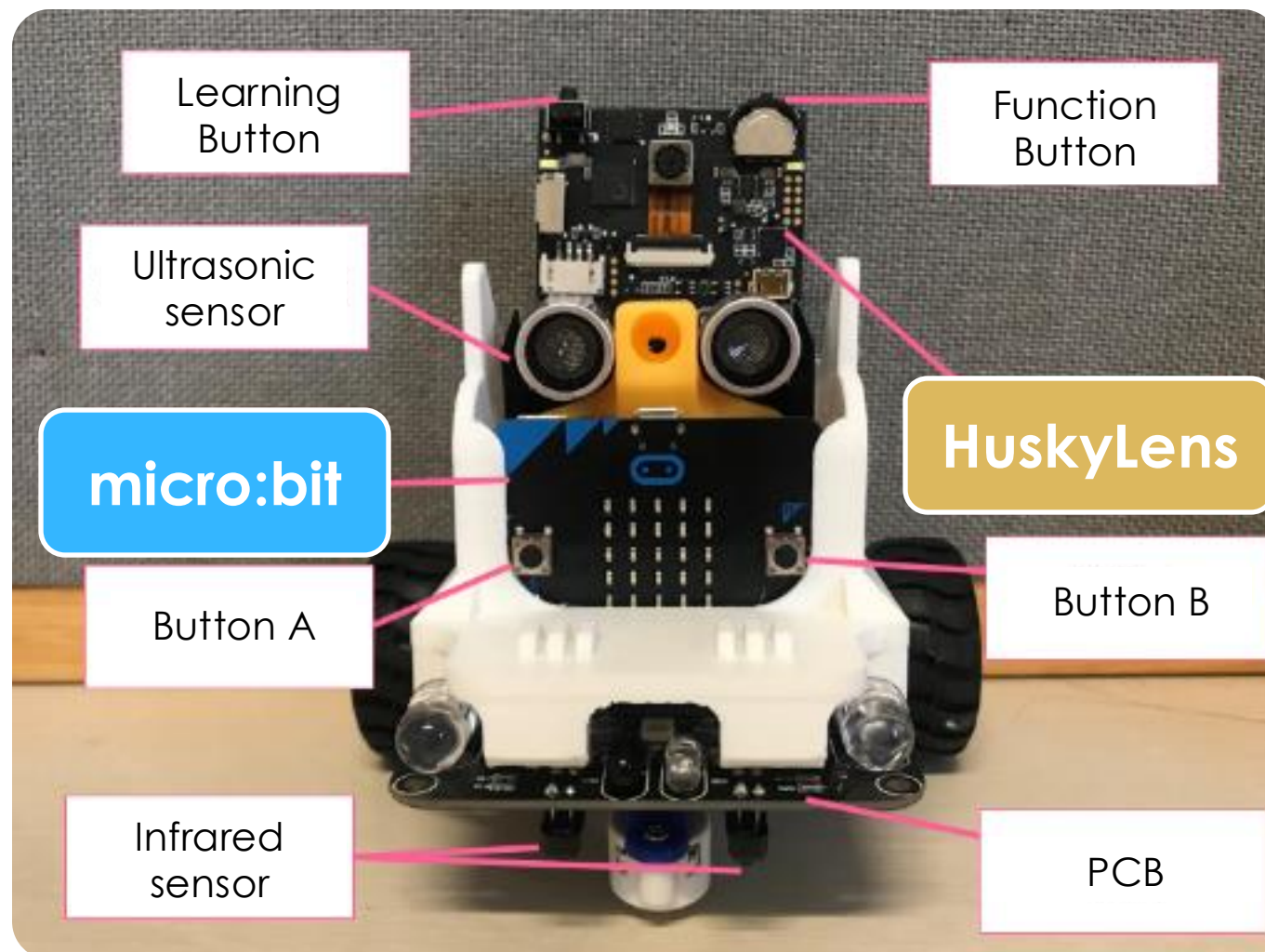
# ● AI Robotic Car - CUHK-JC iCar

- Hardware learning toolkit developed by CUHK research team
- Ideal learning tool for beginners to learn AI





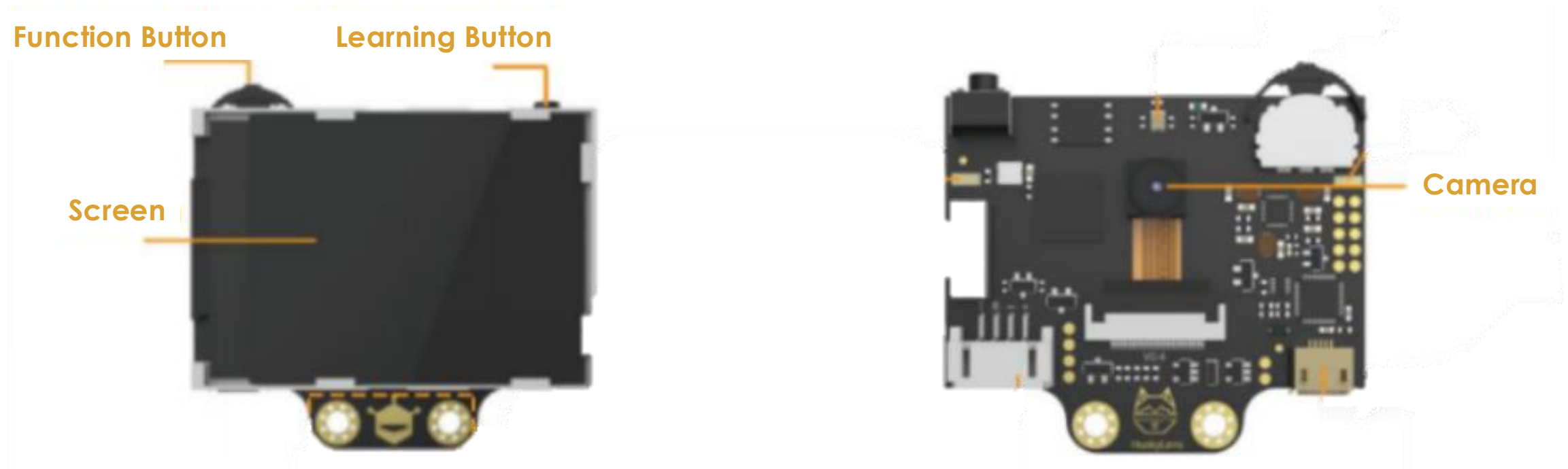
# ● Components of CUHK-JC iCar



# HuskyLens



- AI Visual Sensor





# HuskyLens



- 7 built-in AI functions (Firmware Version : 0.5.1):

## 1.Face Recognition



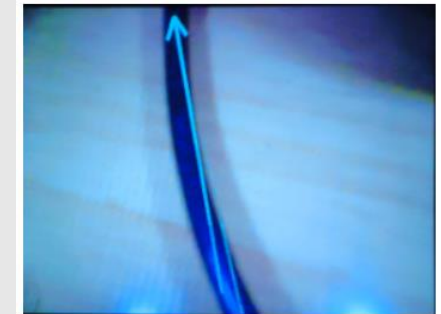
## 2.Object Tracking



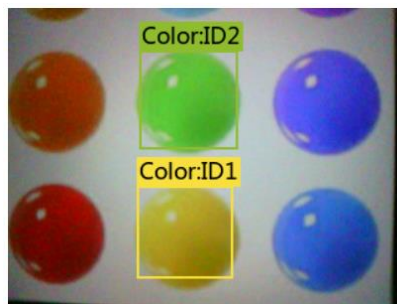
## 3.Object Recognition



## 4.Line Tracking



## 5.Color Recognition



## 6.Tag Recognition



## 7.Object Classification



# Positions of HuskyLens

2 positions of HuskyLens:



1. Facing the front



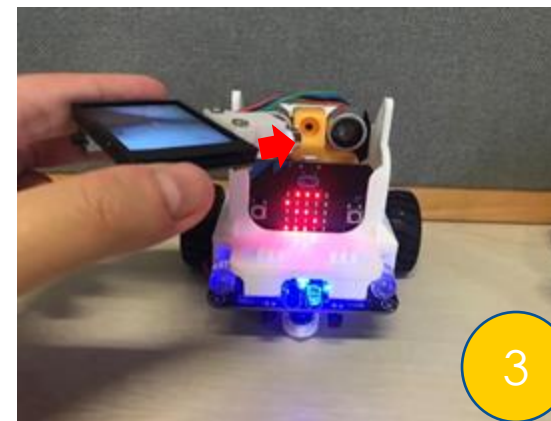
2. Facing the floor



1



2

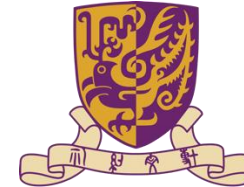


3



4

Position the camera facing the floor



# Activity:

## Moral Dilemma Experiment 道德困境實驗

### Aim:

- To arouse students' **awareness in AI ethics**
- To experience the **factors affecting the data collection**
- To understand the **role of AI in autonomous driving**







1.

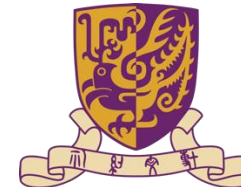
**Moral Dilemma –  
Programming Logic**

2.

**Data Collection &  
Program Testing**

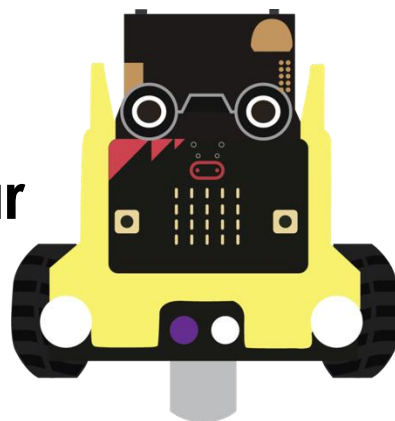
3.

**Discussion** about data  
collection and AI ethics



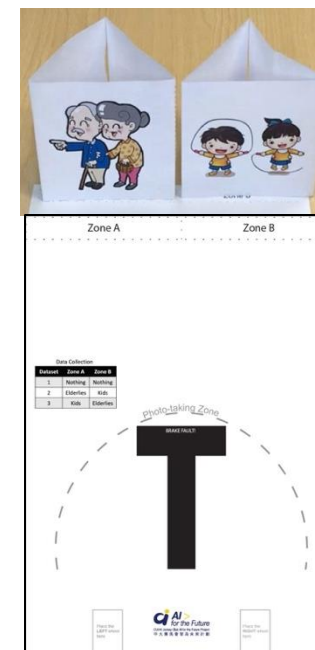
1

CUHK-JC iCar



2

Paper Set up



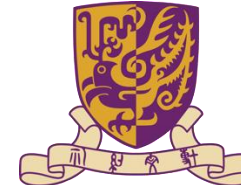
Data Collection		
Student	Zone A	Zone B
1	Nothing	Nothing
2	Nothing	Nothing
3	Nothing	Nothing



# Background of the Experiment

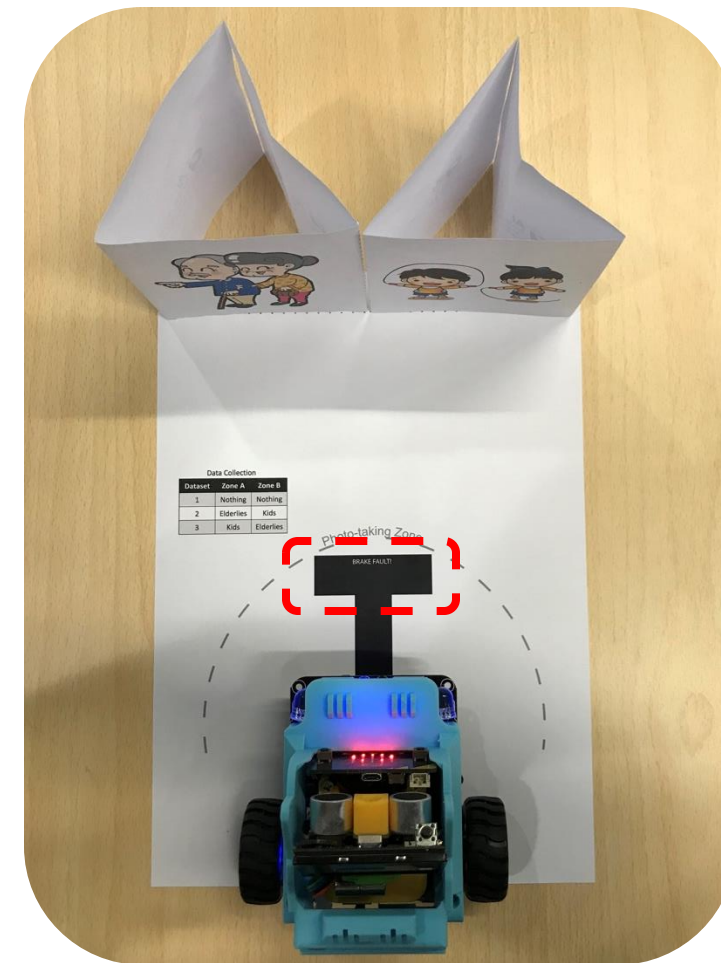
- As autonomous driving technology matures, AI can substitute human drivers

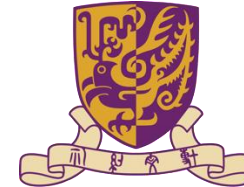




# ● Introduction of the Experiment

- This experiment simulates that the braking system of a self-driving car will fail when it reaches a black horizontal line, and the vehicle can only turn left or right





# ● Introduction of the Experiment

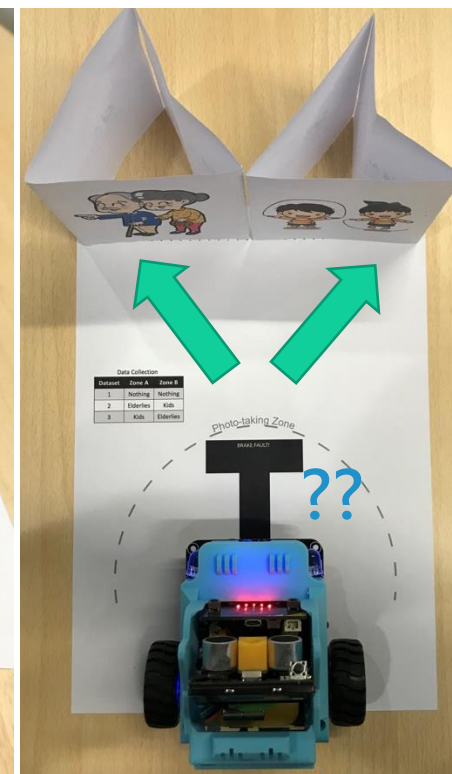
- There are elderlies and kids ahead when the self-driving car is out of control.
- Will you choose to turn left or right?

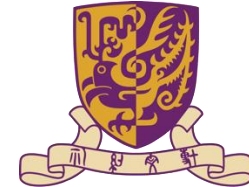
**Decision 1**

**Evade  
Elderlies**

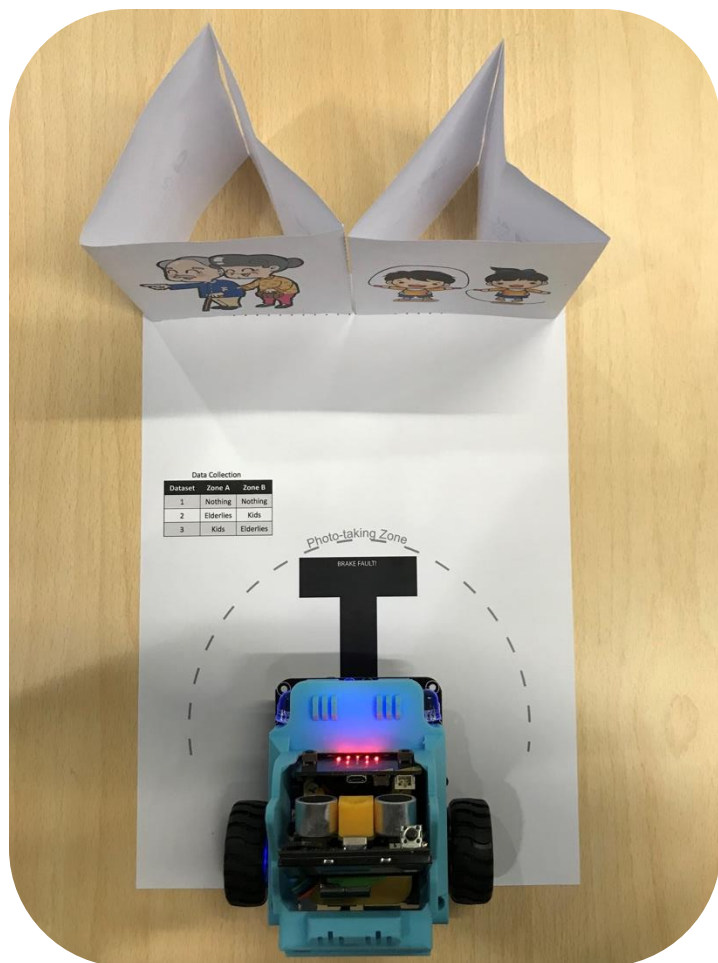
**Decision 2**

**Evade  
Kids**





## Discussion 1: Make Decision



Why did you make this moral decision?

Rehabilitation  
Ability?

Survival Rate? Occupation?

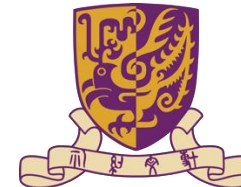
Generation?

Consanguinity?

Contribution?

Wealth?

Other Reasons...?



# Code On MakeCode



Browse <https://makecode.microbit.org/>



makecode



全部

圖片

影片

地圖

新聞

更多

工具

約 2,150,000 項搜尋結果 (0.26 秒)

<https://makecode.microbit.org> ▾ 翻譯這個網頁

**Microsoft MakeCode for micro:bit**

A Blocks / JavaScript code editor for the micro:bit powered by Microsoft **MakeCode**.

開始教程

A Blocks / JavaScript code editor for the micro:bit powered by ...

**Microsoft MakeCode Logo**

A Blocks / JavaScript code editor for the micro:bit powered by ...

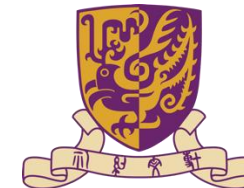
[更多來自microbit.org的搜尋結果 »](#)





## Reminder

Please Set English As The Language!



1. Click



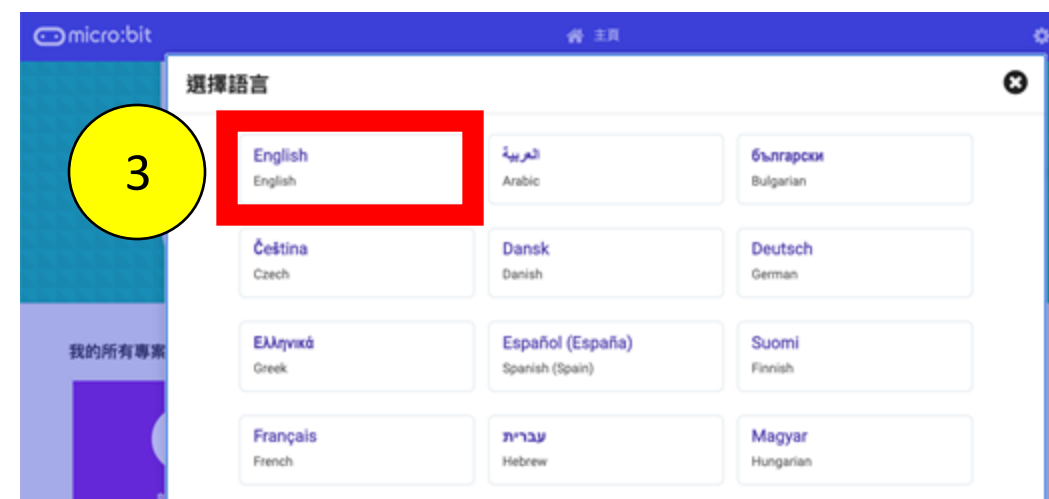
2. Click



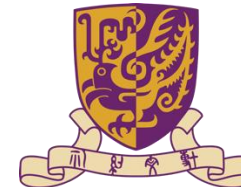
3. Click "English"



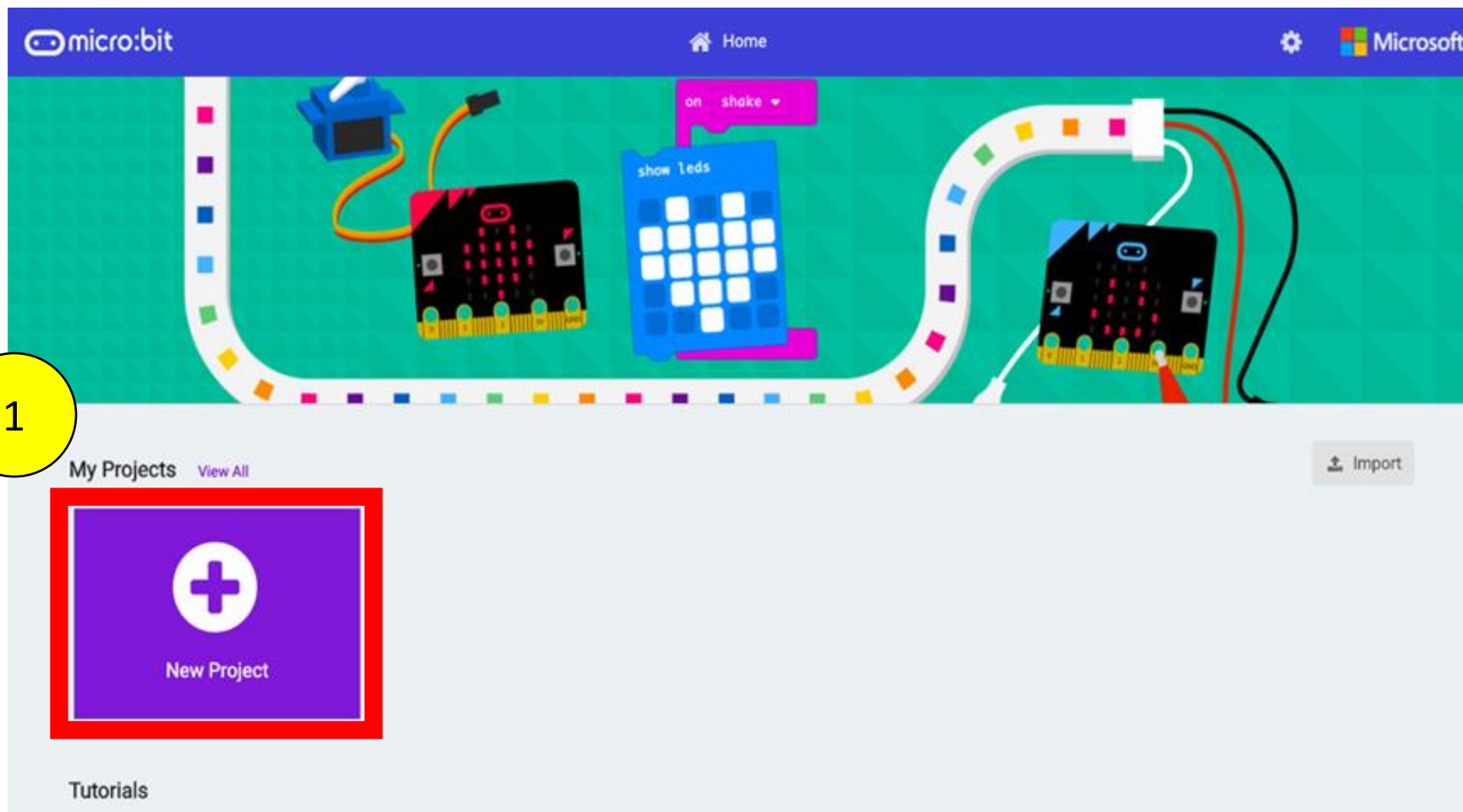
**English must be set as the language, otherwise the program may fail**



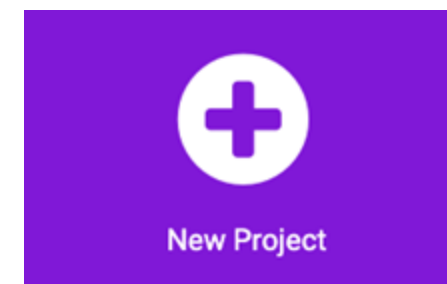


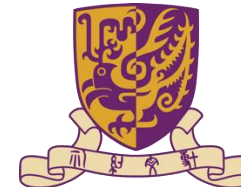


## New Project

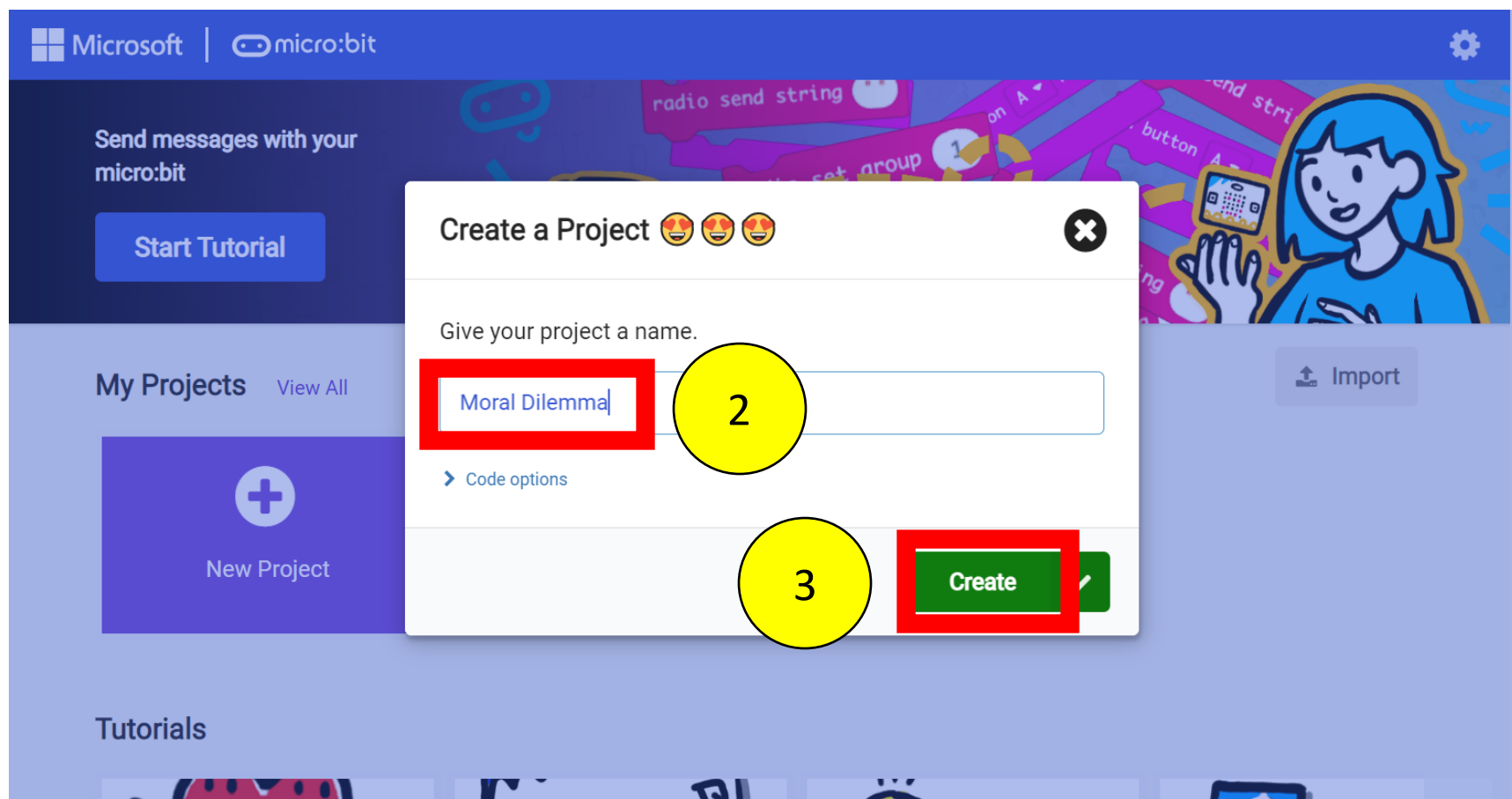


1. Click “New Project”



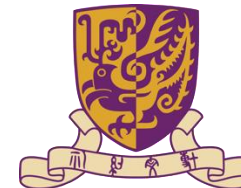


# Create Project

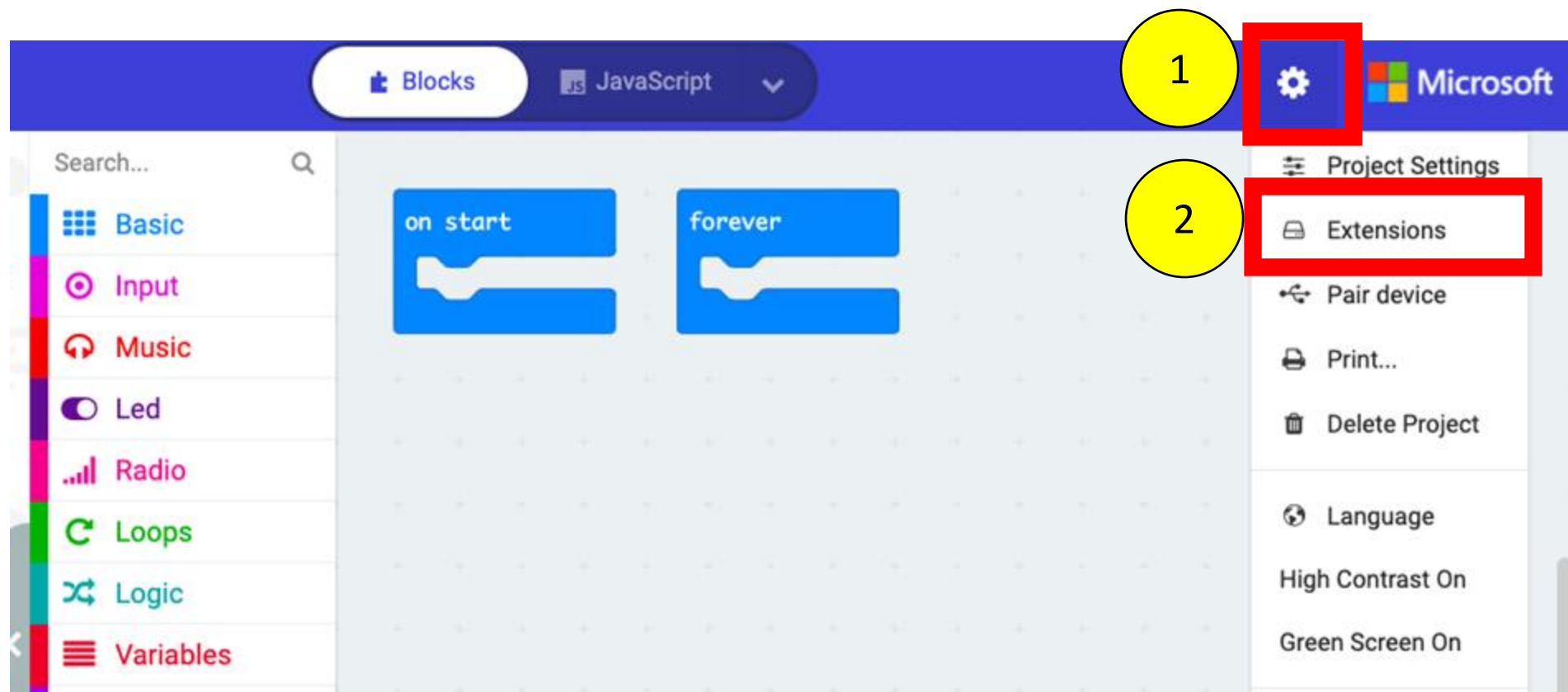


2. Enter “Moral Dilemma”

3. Click **Create**

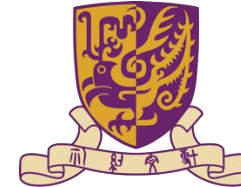


# ● Prepare CUHK-JC iCar Extension

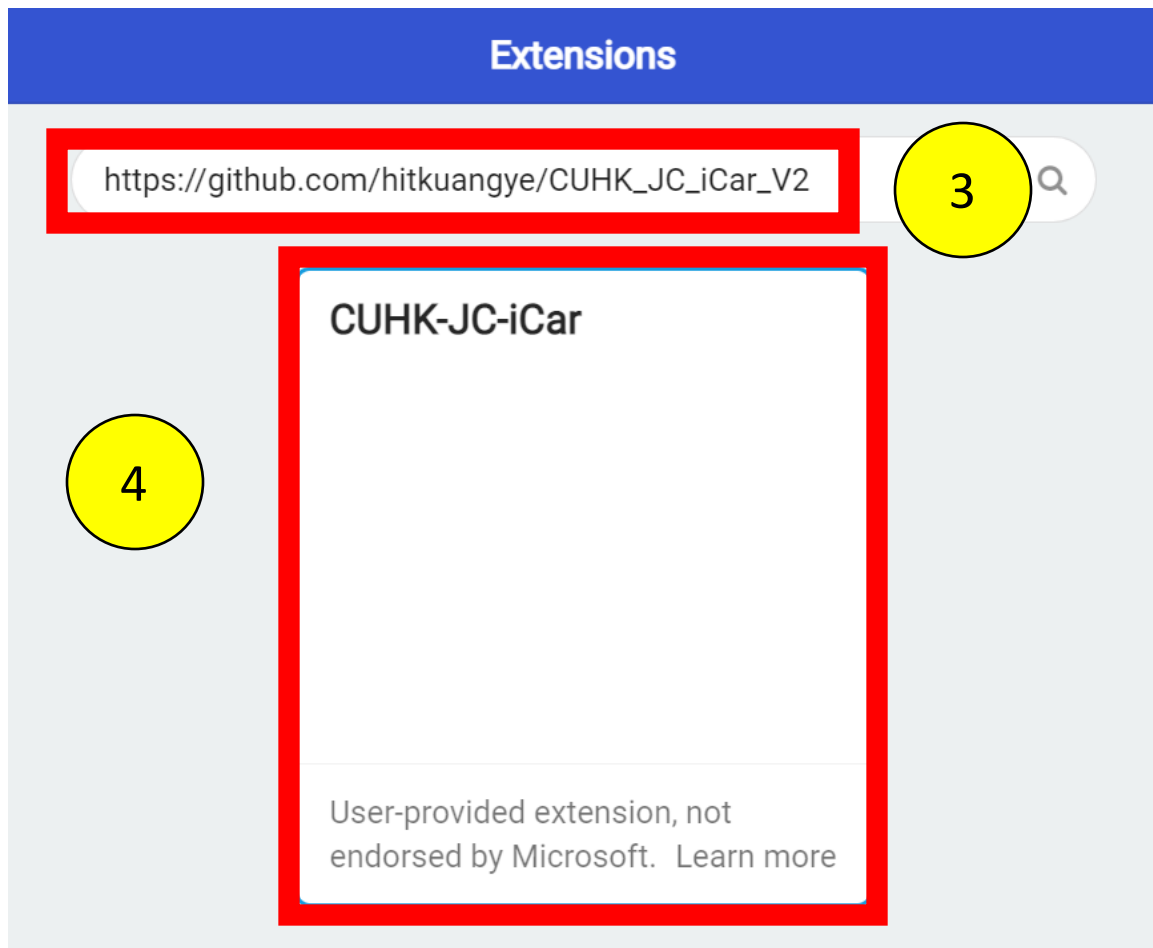


1. Click 

2. Click  Extensions



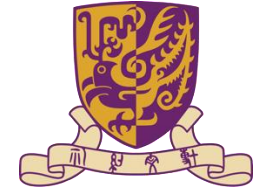
# Import Extension



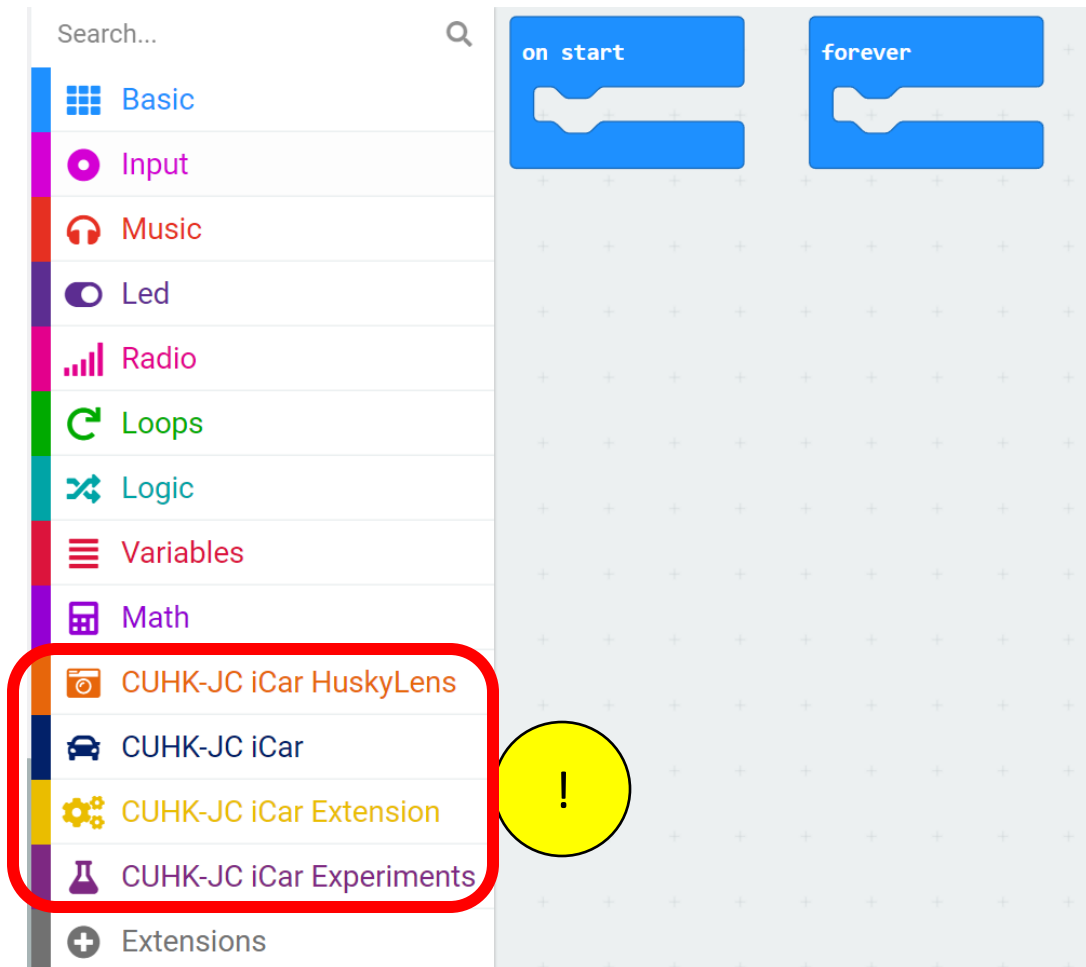
3. Paste the following link:

[https://github.com/hitkuangye/CUHK\\_JC\\_iCar\\_V2](https://github.com/hitkuangye/CUHK_JC_iCar_V2)

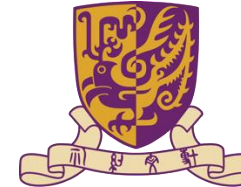
4. Click CUHK-JC-iCar extension



# Import Extension



Extensions are imported

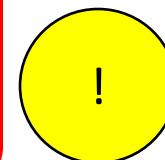


# Playground

Search...

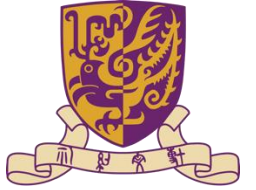
- Basic
- Input
- Music
- Led
- Radio
- Loops
- Logic
- Variables
- Math
- CUHK-JC iCar HuskyLens
- CUHK-JC iCar
- CUHK-JC iCar Extension
- CUHK-JC iCar Experiments
- Extensions

on start forever

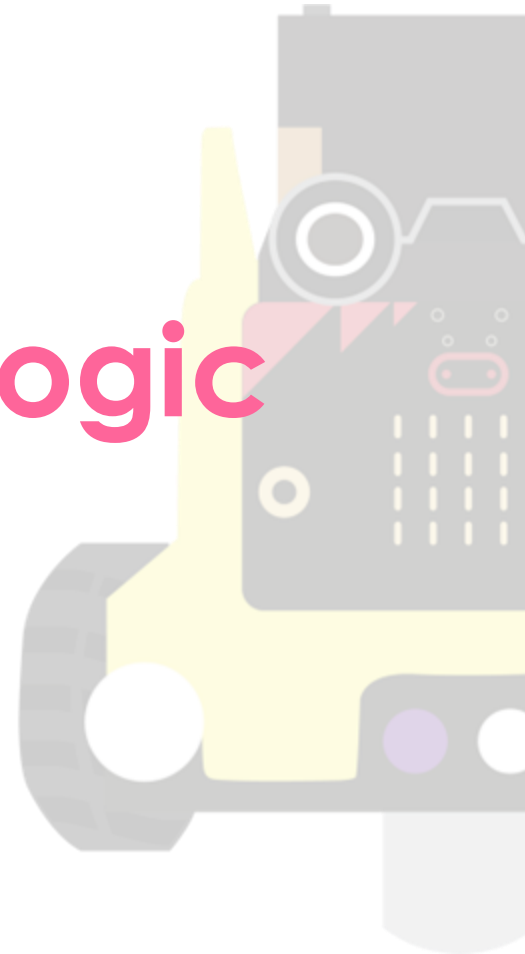


The program will pre-set  
“on start” and “forever” at  
the beginning

We can ignore them for now.  
Please don't delete!



# CUHK-JC iCar Programming Logic





Download the program to CUHK-JC iCar so that it can implement our moral decisions

**Decision 1**

**Evade  
Elderlies**

**Decision 2**

**Evade  
Kids**





# Let's explore the principles behind block programming!



```
on start
  set game_start to 0
  Huskylens initialize I2C until success
  Huskylens switch algorithm to Object Classification
  show icon ***
```

```
forever
  if game_start = 1 then
    pause (ms) 1000
    call Line_Following
    call Read_Huskylens_Data
    call Make_Decision
    set game_start to 1
```

```
on button A pressed
  set game_start to 1
```

Press button A to start the program

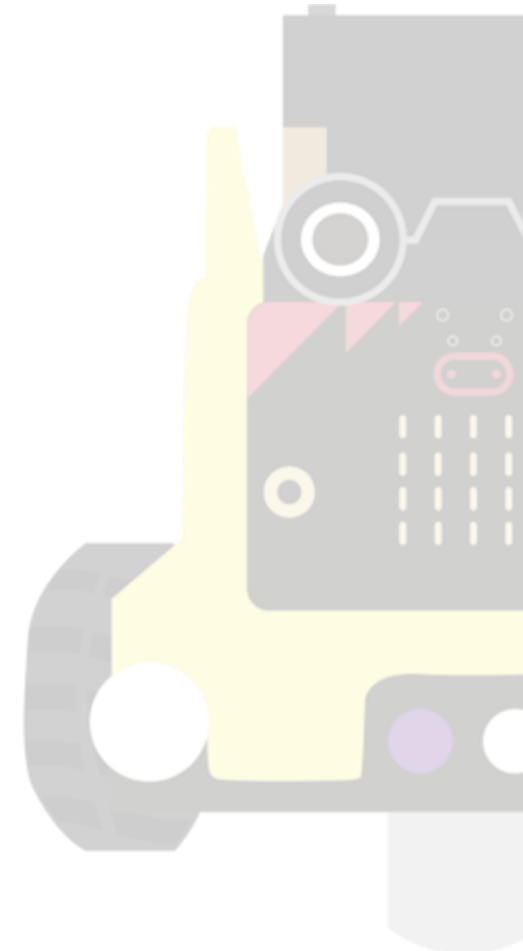
```
function Line_Following
  while true
    do
      if is Left iCar line detector Whiteline ? and is Right iCar line detector Whiteline ? then
        iCar Move Forward at speed 40 %
      else if is Left iCar line detector Whiteline ? and is Right iCar line detector Blackline ? then
        iCar Rotate Right at speed 40 %
      else if is Left iCar line detector Blackline ? and is Right iCar line detector Whiteline ? then
        iCar Rotate Left at speed 40 %
      else if is Left iCar line detector Blackline ? and is Right iCar line detector Blackline ? then
        iCar Stop
      break
```

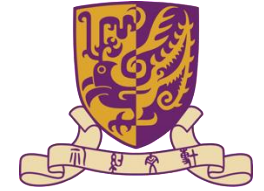
```
function Read_Huskylens_Data
  while true
    do
      Huskylens request data once and save into the result
      if Huskylens check if ID 2 frame is on screen from the result or Huskylens check if ID 3 frame is on screen from the result then
        break
```

```
function Make_Decision
  if Huskylens check if ID 2 frame is on screen from the result then
    show number 2
    call Turn_Right
    ID2 means the elderly are on the left
  else if Huskylens check if ID 3 frame is on screen from the result then
    show number 3
    call Turn_Left
    ID3 means the elderly are on the right
```

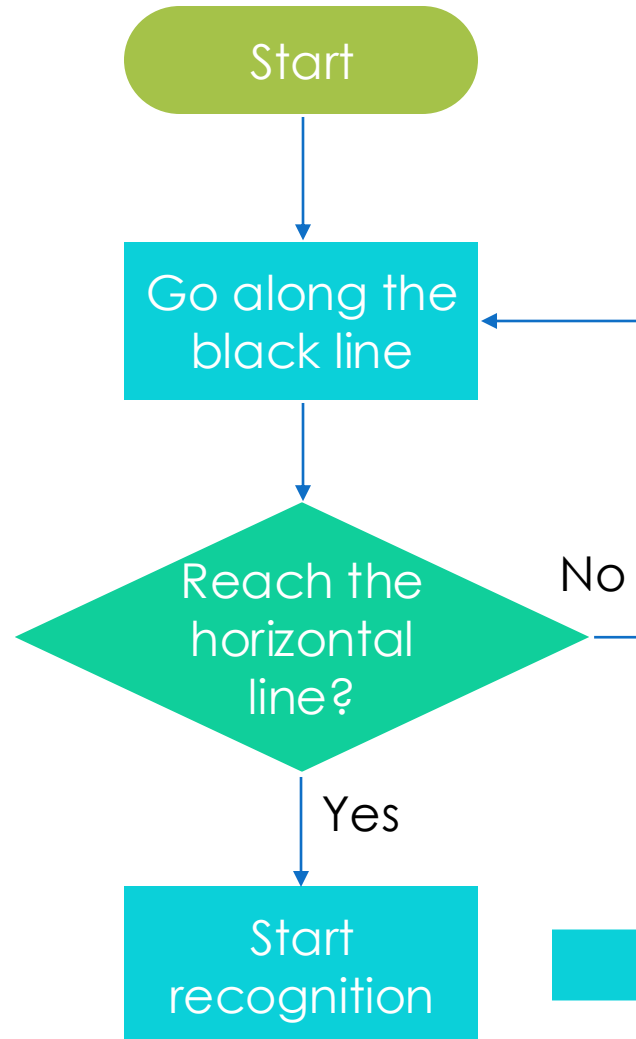
```
function Turn_Left
  iCar Turn Left at speed 70 %
  pause (ms) 200
  iCar Move Forward at speed 60 %
  pause (ms) 1000
  iCar Stop
```

```
function Turn_Right
  iCar Turn Right at speed 70 %
  pause (ms) 200
  iCar Move Forward at speed 60 %
  pause (ms) 1000
  iCar Stop
```

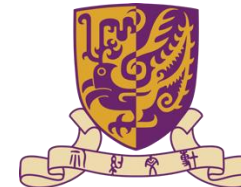




# Program Flowchart



Situation	Zone A	Zone B	Image
1	Elderlies	Kids	
2	Kids	Elderlies	



## Decision 1 Evade Elderlies

## Decision 2 Evade Kids

Situation

Image

1



2



Start  
recognition

Recognized  
Situation 1?

No

Yes

Turn **Right**

Turn  
**Left**

Start  
recognition

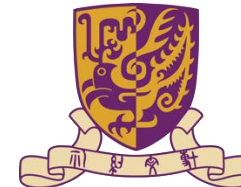
Recognized  
Situation 1?

No

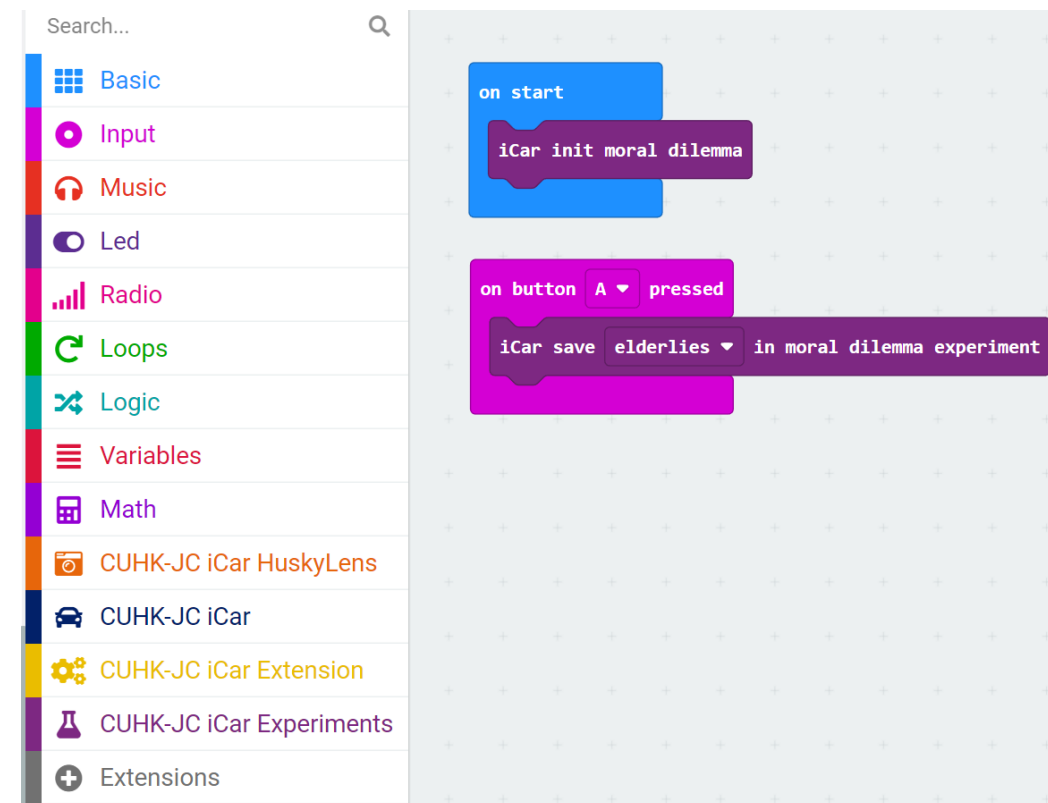
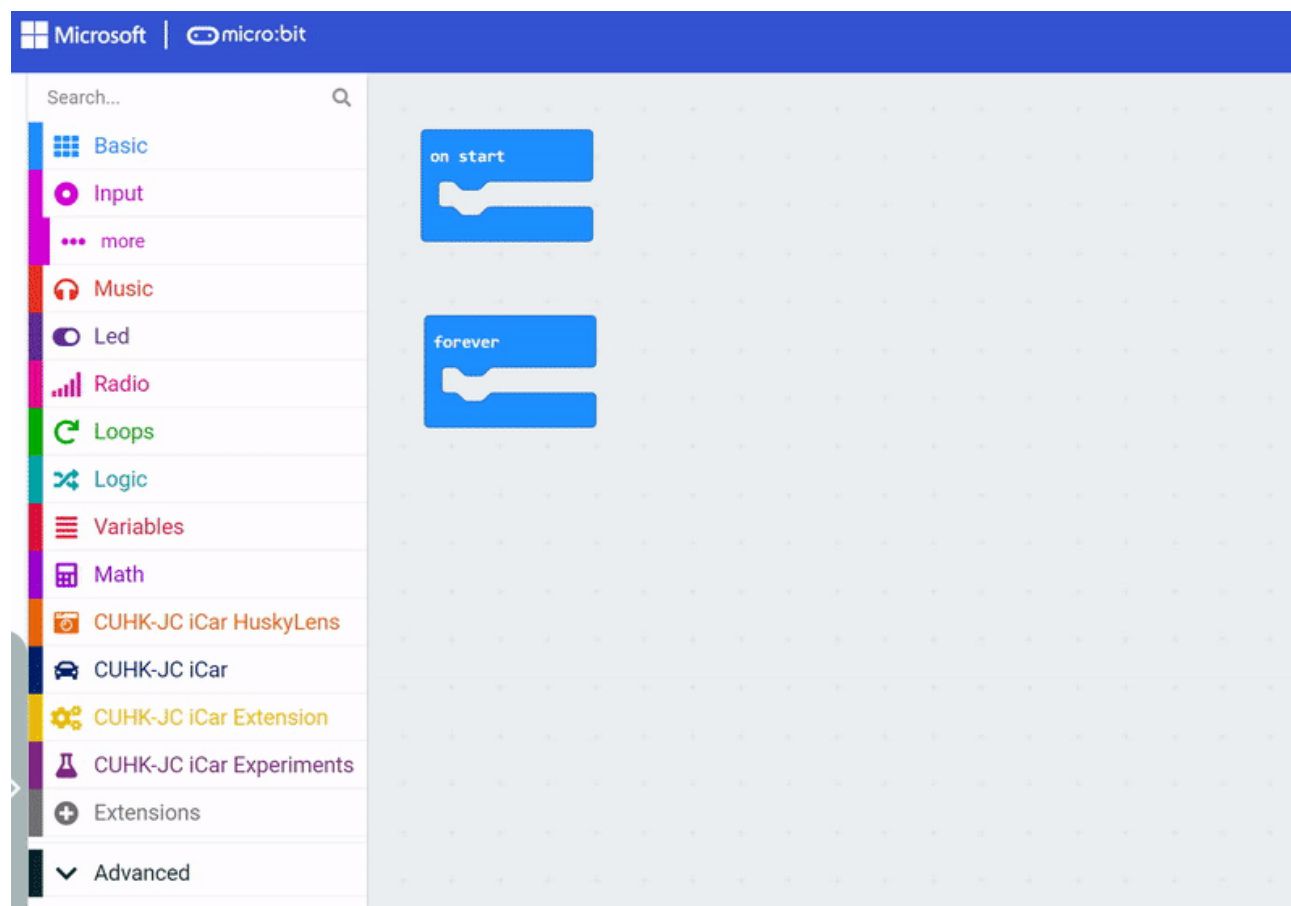
Yes

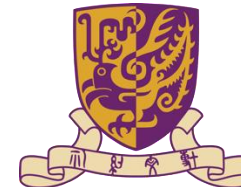
Turn  
**Left**

Turn **Right**



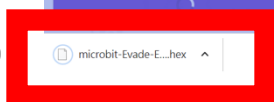
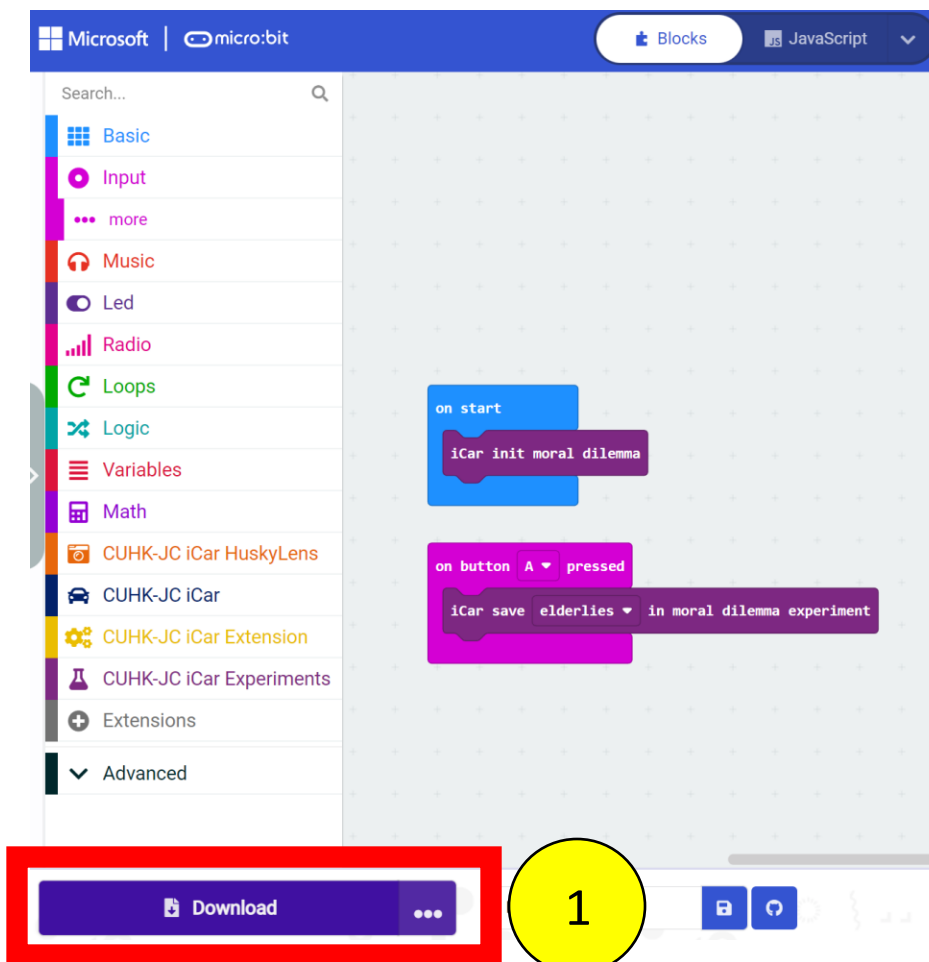
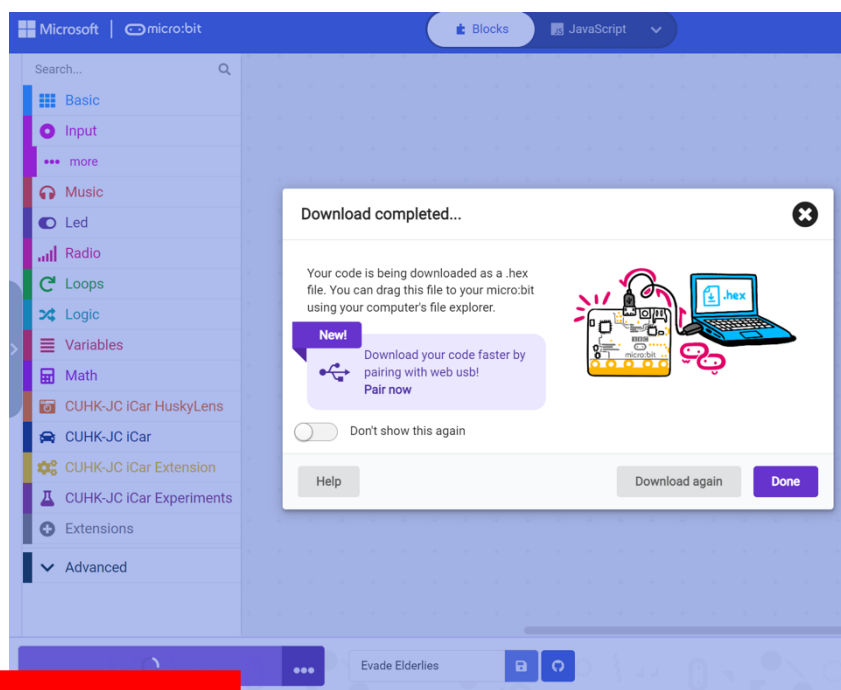
# To save time....

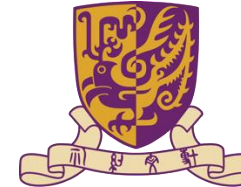




# Download The Program To CUHK-JC iCar

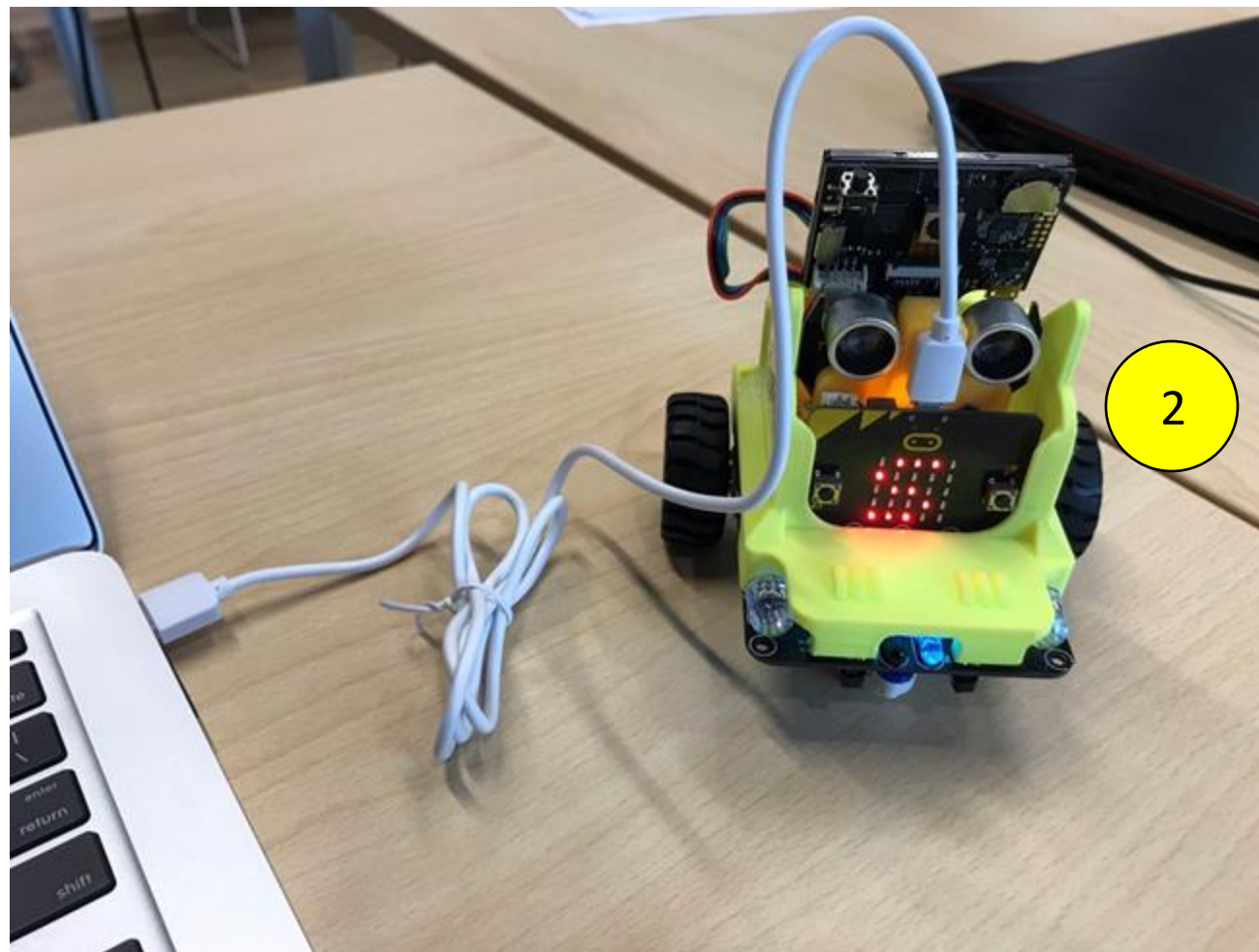
Step 1: Click  Download

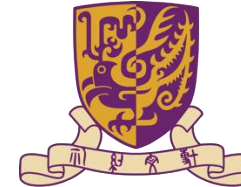




## Download The Program To CUHK-JC iCar

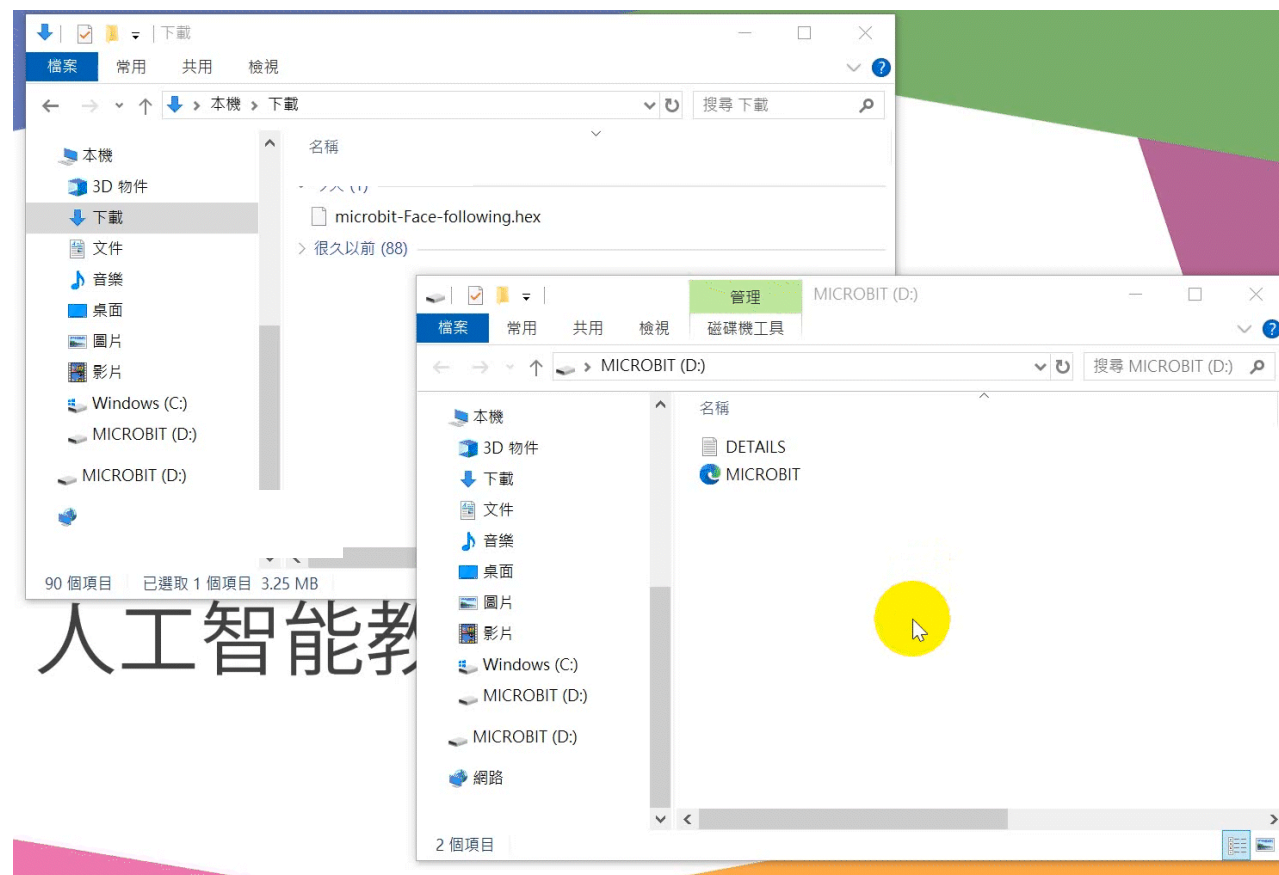
- Step 2: Connect the micro:bit to computer by a micro USB cable



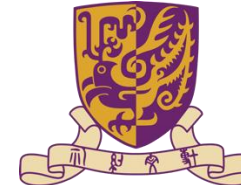


# Download The Program To CUHK-JC iCar

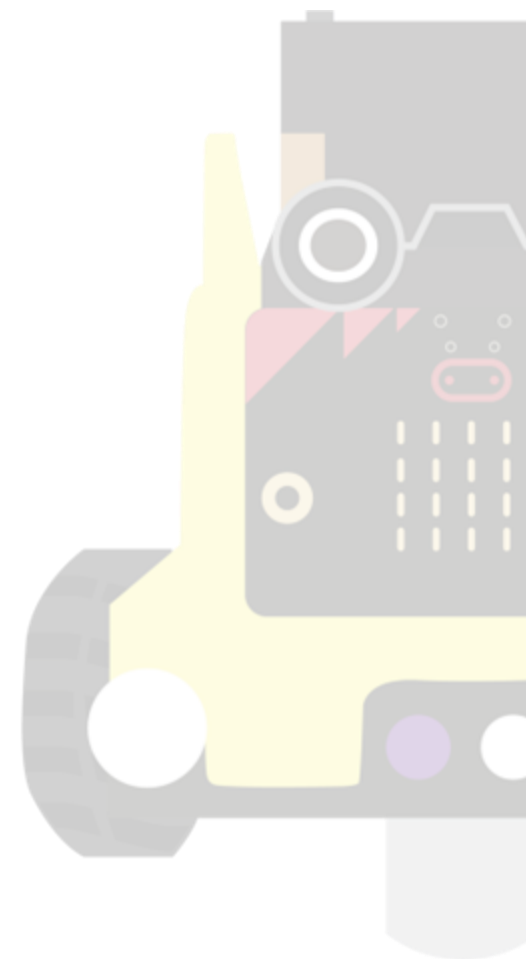
- Step 3: Drag the “mircobit-Evade-elderlies.hex” file into the micro:bit window



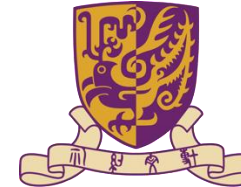




# Data Collection







# ● Data Collection

Now watch carefully the staff's demonstration...

## 1. Collect 3 sets of data

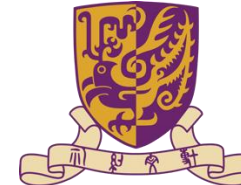
Dataset	Zone A	Zone B
1	Nothing	Nothing
2	Elderlies	Kids
3	Kids	Elderlies

## 2. Remember to collect at least 30 photos for each set of data

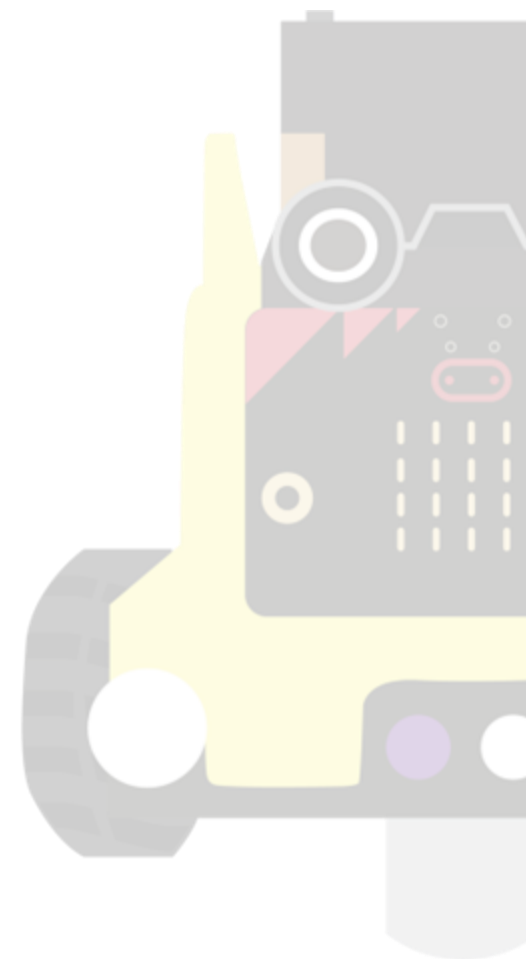




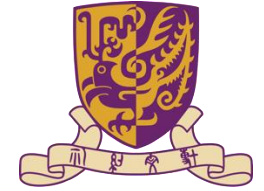
Let's try  
data collection



# Try your Program

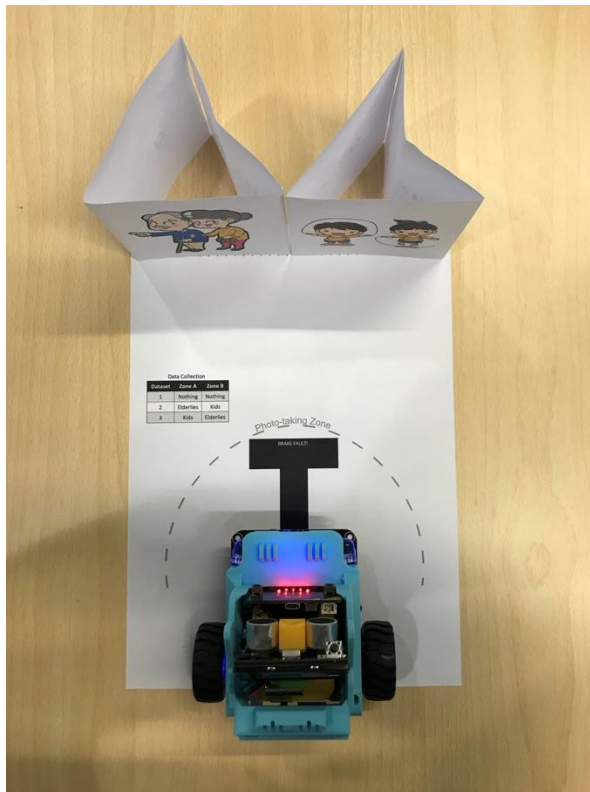






## Try your Program

- Step 1: Place the paper models in the designated zones and place CUHK-JC iCar on the markings

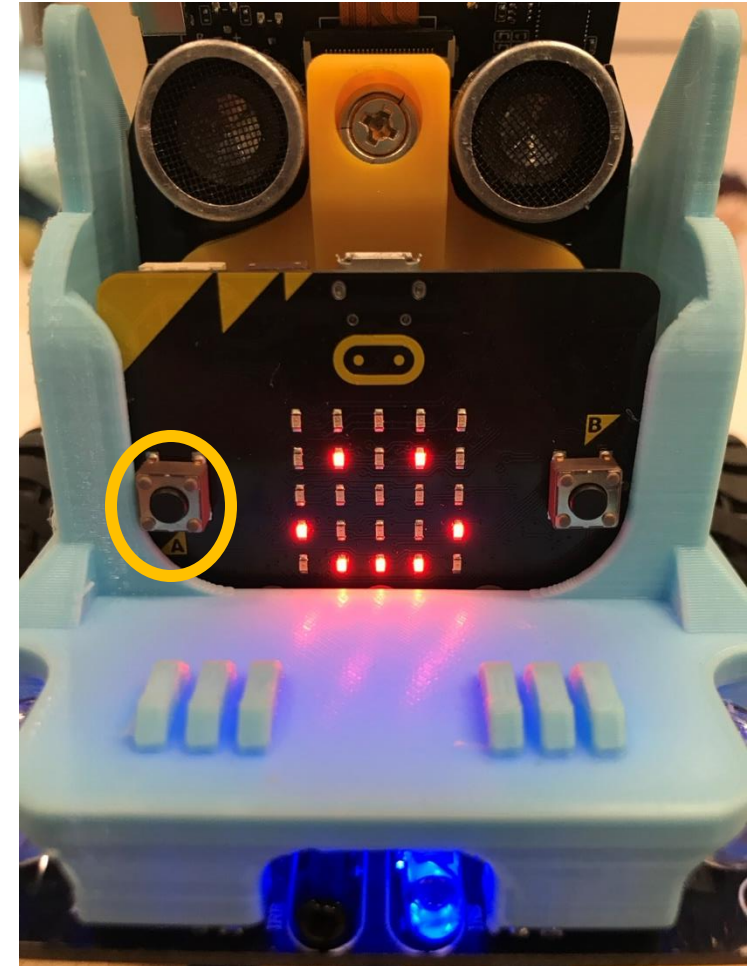


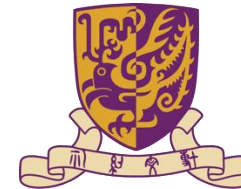
Attention:  
Place the 2 wheels  
according to the  
markings on the  
paper



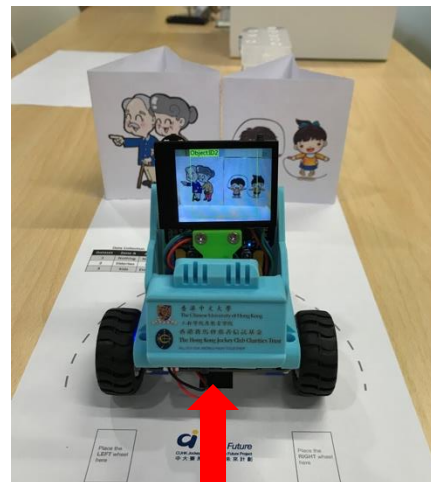
## ● Try your Program

- Step 2: Press **button A** on micro:bit





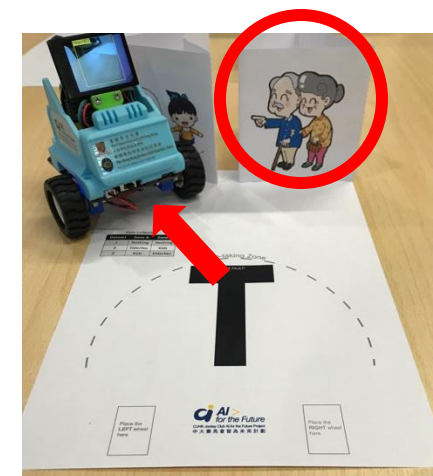
# Simulation Program: Evade Elderlies



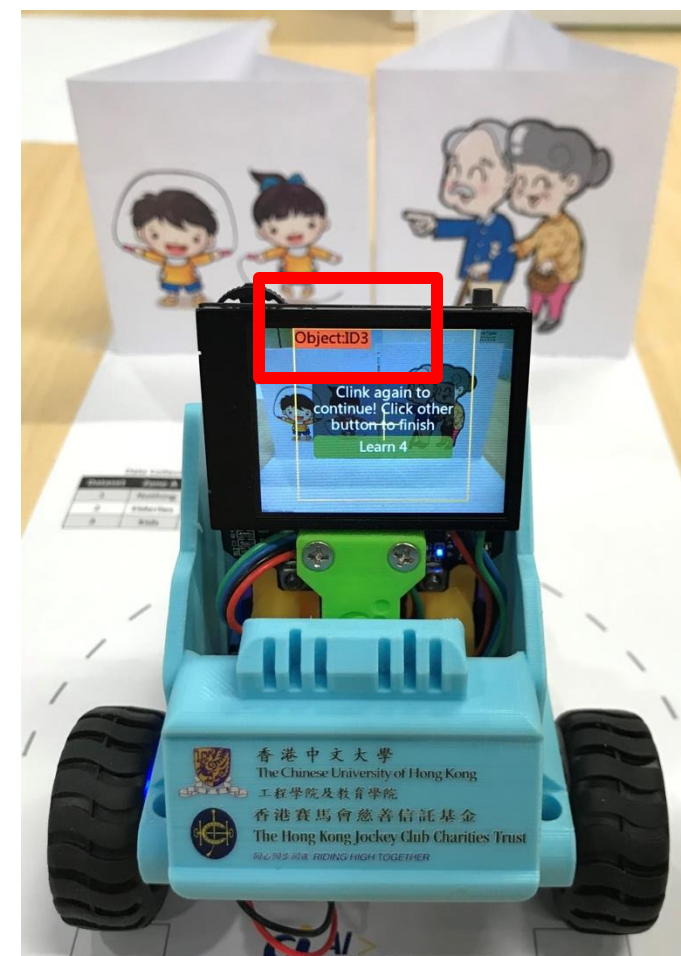
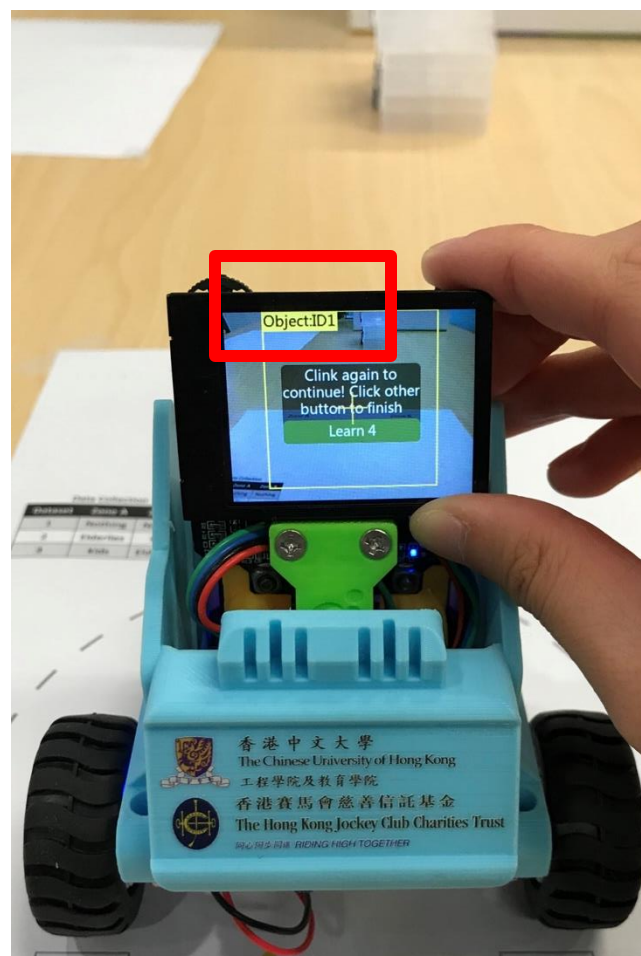
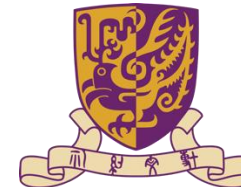
ID2



ID3











Let's try  
Your program

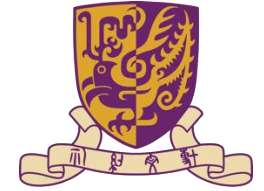


## Discussion 2: Data Collection

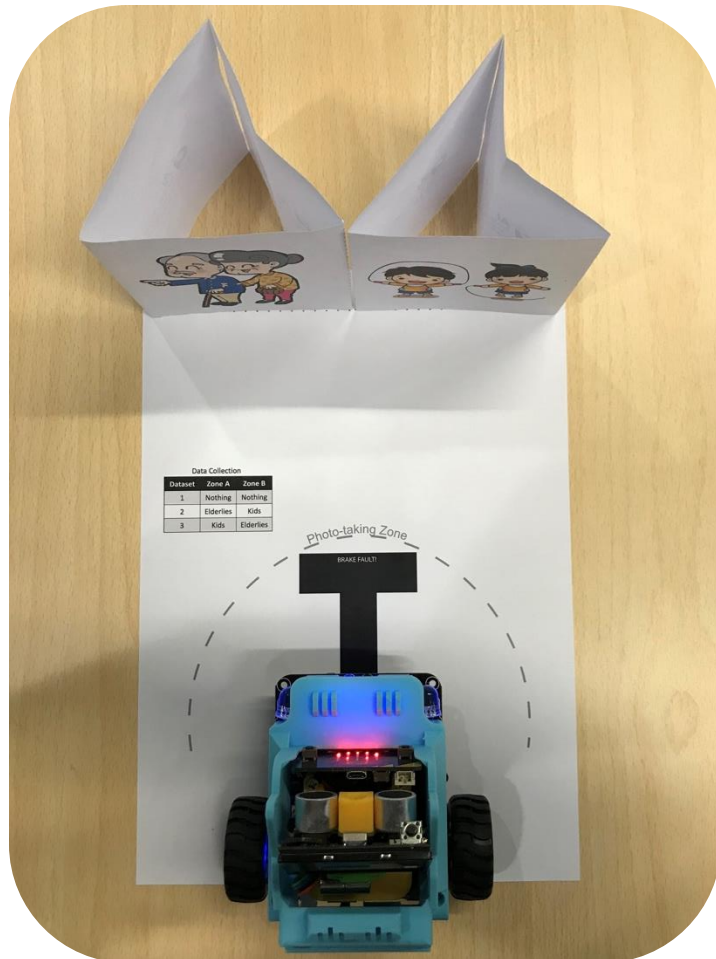
- Why do we need to take at least 30 images for each dataset?
- Why do we need to move left and right when shooting?
- What factors will affect the judgment of artificial intelligence?

### Try More Situations

- Different backgrounds
- Different data sizes
- Different datasets
- Different orientations of the object
- Bad data collection (zoom in/out)
- Different presentation methods (sound, lights, ultrasonic sensor, IR sensors, motors)



## Discussion 3: Other Decisions



Can you think of decision 3?

**Decision 1**

**Evade  
Elderlies**

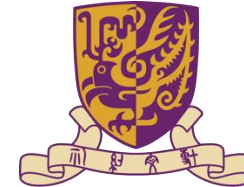
**Decision 2**

**Evade  
Kids**

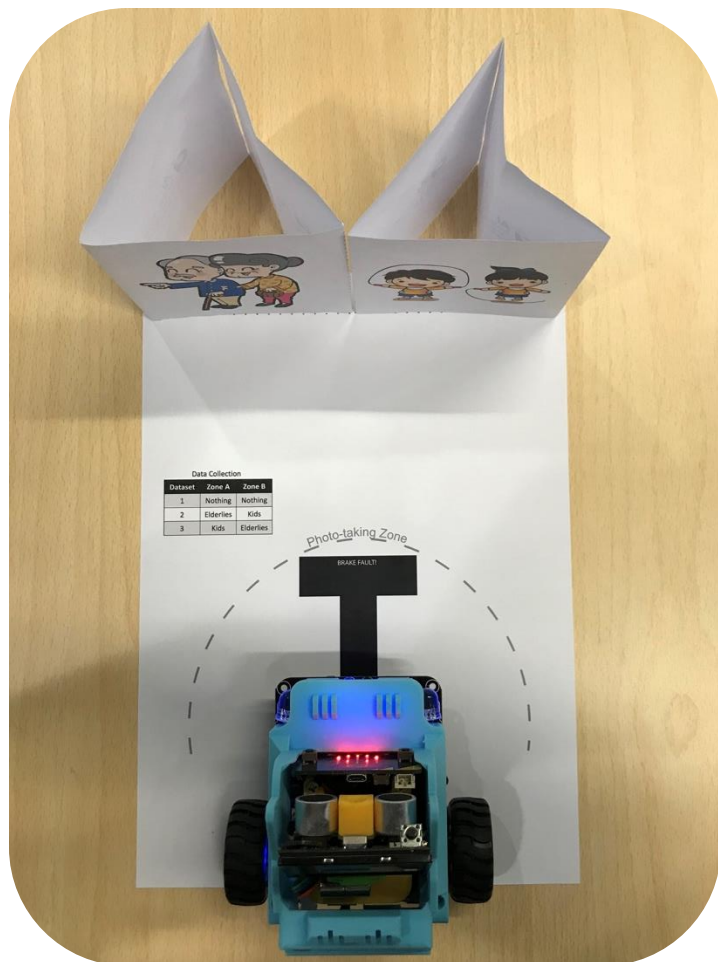
**Decision 3**

**?**





## Discussion 4: Other Decisions



**Can AI help us make decisions?**

**AI can make distinctions for us, but it can only operate according to programs written by programmers**

**Programmer is always the one who makes the final decision on a moral dilemma**